

Statistical inference for Bifurcating Markov Chains

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Content

- ▶ Some technical remarks about variance estimates for geometrically ergodic Markov chains
- ▶ Bifurcating Markov Chains (BMC)
- ▶ Deviation bounds for uniformly geometrically ergodic BMC
- ▶ Estimation in BMC: invariant density, mean transition and transition densities
- ▶ Application in a transport-fragmentation model

MC setting

- ▶ $(X_n)_{n \geq 0}$ homogeneous MC with state space $(\mathcal{S}, \mathfrak{G})$ and transition \mathcal{P} .
- ▶ **Assumption (UE)** there exists a unique invariant probability ν ($\nu\mathcal{P} = \nu$) such that for all $m \geq 0$:

$$|\mathcal{P}^m \phi(x) - \nu(\phi)| \leq R|\phi|_{\infty} \rho^m \text{ for all } x \in \mathcal{S}$$

with $0 < \rho < 1$ and $R > 0$.

- ▶ Actually a *very strong* assumption: uniform geometric ergodicity v.s. geometric ergodicity

Objective

- ▶ Let ϕ with $\nu(\phi) = 0$ and $\mathcal{E}_n(\phi) := n^{-1} \sum_{i=1}^n \phi(X_i)$.
- ▶ Objective: control of $V_n(\phi) := \mathbb{E}_\nu [\mathcal{E}_n(\phi)^2]$.
- ▶ In the IID case,

$$V_n(\phi) = n^{-1} |\phi|_{L^2(\nu)}^2.$$

- ▶ In the general Markov case, we have an additional covariance term

$$\begin{aligned} 2n^{-2} \sum_{i < j} \mathbb{E}_\nu [\phi(X_i) \phi(X_j)] &= 2n^{-2} \sum_{i < j} \mathbb{E}_\nu [\phi(X_i) \mathcal{P}^{j-i} \phi(X_i)] \\ &= 2n^{-2} \sum_{i < j} \nu(\phi \mathcal{P}^{j-i} \phi) \end{aligned}$$

Covariance control in the Markov case

- ▶ We have by **(UE)**

$$|\nu(\phi \mathcal{P}^{j-i} \phi)| \lesssim |\phi|_\infty |\phi|_{L^1(\nu)} \rho^{j-i}.$$

- ▶ It follows that

$$\begin{aligned} 2n^{-2} \sum_{i < j} \mathbb{E}_\nu [\phi(X_i) \phi(X_j)] &\lesssim n^{-1} |\phi|_\infty |\phi|_{L^1(\nu)} n^{-1} \sum_{i \neq j} \rho^{j-i} \\ &\lesssim n^{-1} |\phi|_\infty |\phi|_{L^1(\nu)} \end{aligned}$$

- ▶ Finally

$$V_n(\phi) := \mathbb{E}_\nu [\mathcal{E}_n(\phi)^2] \lesssim n^{-1} (|\phi|_{L^2(\nu)}^2 + |\phi|_\infty |\phi|_{L^1(\nu)})$$

- ▶ Nonparametrically-wise, we are happy.

The Markov case on a binary tree

- ▶ Binary tree

$$\mathbb{T}_n = \bigcup_{m=0}^n \mathbb{G}_m, \quad \mathbb{G}_m = \{0, 1\}^m.$$

- ▶ Notation $\mathbb{T} = \bigcup_{m=0}^{\infty} \mathbb{G}_m$ and $|u| = m$ if $u \in \mathbb{T}$ and $u \in \mathbb{G}_m$.
- ▶ $|\mathbb{T}_m| = 2^{m+1} - 1 \lesssim 2^m$ and $|\mathbb{G}_m| = 2^m$.
- ▶ Let $(X_u)_{u \in \mathbb{T}}$ be a Markov chain indexed by \mathbb{T} under **(UE)**.
- ▶ With ϕ such that $\nu(\phi) = 0$, how does

$$V_n(\phi) = \mathbb{E}_{\nu} \left[\left(|\mathbb{T}_n|^{-1} \sum_{u \in \mathbb{T}_n} \phi(X_u) \right)^2 \right]$$

behave?

First variance estimate

- ▶ Decompose the sum along generations. Set

$$Y_m(\phi) = \sum_{u \in \mathbb{G}_m} \phi(X_u) \text{ so that } \sum_{u \in \mathbb{T}_n} \phi(X_u) = \sum_{m=0}^n Y_m(\phi).$$

- ▶ We have (triangle inequality)

$$V_n(\phi) = |\mathbb{T}_n|^{-2} \mathbb{E}_\nu \left[\left(\sum_{m=0}^n Y_m(\phi) \right)^2 \right] \leq |\mathbb{T}_n|^{-2} \left(\sum_{m=0}^n \mathbb{E}_\nu [Y_m(\phi)^2] \right)^{1/2}$$

- ▶ Next step: control of $\mathbb{E}_\nu [Y_m(\phi)^2]$.

Control of $\mathbb{E}_\nu [Y_m(\phi)^2]$

- ▶ $\mathbb{E}_\nu [Y_m(\phi)^2] = I + II$, with $I = |\mathbb{G}_m| \nu(\phi^2)$ and

$$\begin{aligned} II &= \sum_{u \neq v, u, v \in \mathbb{G}_m} \mathbb{E}_\nu [\phi(X_u)\phi(X_v)] \\ &= \sum_{u \neq v, u, v \in \mathbb{G}_m} \mathbb{E}_\nu \left[\mathbb{E}_\nu[\phi(X_u) | \mathcal{F}_{|u \wedge v|}] \mathbb{E}_\nu[\phi(X_v) | \mathcal{F}_{|u \wedge v|}] \right] \\ &= \sum_{u \neq v, u, v \in \mathbb{G}_m} \mathbb{E}_\nu \left[\mathcal{P}^{|u| - |u \wedge v|} \phi(X_{u \wedge v}) \mathcal{P}^{|v| - |u \wedge v|} \phi(X_{u \wedge v}) \right] \end{aligned}$$

- ▶ $u \wedge v =$ most recent common ancestor of u and v .

Control of $\mathbb{E}_\nu[Y_m(\phi)^2]$ (cont.)

- ▶ Re-index the sum on $u \neq v$, $|u| = |v| = m$ as a functional of $X_{u \wedge v}$:

$$\{(u, v) \in \mathbb{G}_m^2\} = \bigcup_{\ell=1}^m \{(u, v) \in \mathbb{G}_m^2, u \wedge v = m - \ell\}$$

- ▶ $|\{(u, v) \in \mathbb{G}_m^2, u \wedge v = m - \ell\}| \lesssim 2^{2\ell} |\mathbb{G}_{m-\ell}|$.
- ▶ We obtain

$$\begin{aligned} II &= \sum_{u \neq v, u, v \in \mathbb{G}_m} \mathbb{E}_\nu \left[\mathcal{P}^{|u|-|u \wedge v|} \phi(X_{u \wedge v}) \mathcal{P}^{|u|-|u \wedge v|} \phi(X_{u \wedge v}) \right] \\ &= \sum_{\ell=1}^m 2^{2\ell-1} \mathbb{E}_\nu \left[\sum_{w \in \mathbb{G}_{m-\ell}} (\mathcal{P}^\ell \phi)(X_w)^2 \right] \\ &\lesssim 2^m \sum_{\ell=1}^m 2^\ell \nu \mathcal{P}^{m-\ell} ((\mathcal{P}^\ell \phi)^2). \end{aligned}$$

Too quick estimates

- ▶ Now, we have $(\mathcal{P}^\ell \phi)^2 \lesssim |\phi|_\infty^2 \rho^{2\ell}$ and

$$II \lesssim 2^m \sum_{\ell=1}^m (2\rho^2)^\ell |\phi|_\infty^2 \lesssim 2^m |\phi|_\infty^2 \quad (\text{provided } \rho < \frac{\sqrt{2}}{2})$$

- ▶ Putting together $I + II$ plus taking $\sqrt{\cdot}$, we obtain

$$\mathbb{E}_\nu [Y_m(\phi)^2]^{1/2} \lesssim 2^{m/2} \sqrt{|\phi|_{L^2(\nu)}^2 + |\phi|_\infty^2},$$

so $(\sum_{m=0}^n 2^{m/2} \sqrt{\cdot})^2 \lesssim |\mathbb{T}_n| (|\phi|_{L^2(\nu)}^2 + |\phi|_\infty^2)$ and finally

$$V_n(\phi) \lesssim |\mathbb{T}_n|^{-1} (|\phi|_{L^2(\nu)}^2 + |\phi|_\infty^2)$$

- ▶ Nonparametrically-wise, we are NOT happy...

Reversible (L^2) vs nonreversible (L^∞) theory

- ▶ Where do we lose? We have $(\mathcal{P}^\ell \phi)^2 \lesssim |\phi|_\infty^2 \rho^{2\ell}$ because of **(UE)**.
- ▶ If we had a reversible process, we could hope for

$$(\mathcal{P}^\ell \phi)^2 \lesssim |\phi|_{L^2}^2 \rho^{2\ell}.$$

- ▶ Solution: we can sacrifice *some of* the geometric ergodicity if we have some *regularization* of \mathcal{P} : for $\ell \geq 1$

$$|\mathcal{P}^\ell \phi|_\infty \leq |\mathcal{P}\phi|_\infty$$

and for a nice state space (hereafter $\mathcal{S} = \mathbb{R}$)

$$\begin{aligned} |\mathcal{P}\phi(x)| &= \left| \int_{\mathcal{S}} \phi(y) \mathcal{P}(x, dy) \right| \stackrel{!}{=} \left| \int_{\mathcal{R}} \phi(y) \mathcal{P}(x, y) dy \right| \\ &\leq \sup_{x \in \mathcal{S}, y \in \text{supp}\phi} \mathcal{P}(x, y) |\phi|_{L^1(\text{Leb})} \end{aligned}$$

Toward a compromise between the action of \mathcal{P} and **(UE)**

- ▶ Under this additional regularity property on \mathcal{P}

$$|\mathcal{P}^\ell \phi(x)| \lesssim |\phi|_{L^1(\text{Leb})} \wedge |\phi|_\infty \rho^\ell.$$

- ▶ Trade-off in the control of the covariance term II of $\mathbb{E}_\nu [Y_m(\phi)^2]$:

$$\begin{aligned} II &\lesssim 2^m \sum_{\ell=1}^{\ell^*} 2^\ell |\phi|_{L^1(\text{Leb})}^2 + 2^m \sum_{\ell=\ell^*+1}^m (2\rho^2)^\ell |\phi|_\infty^2 \\ &\lesssim 2^m \inf_{\ell^*} (2^{\ell^*} |\phi|_{L^1(\text{Leb})}^2 + (2\rho^2)^{\ell^*} |\phi|_\infty^2) \end{aligned}$$

and optimise in ℓ^* ...

- ▶ Nonparametrically-wise, we are happy again: if $\phi(x) = h^{-1} \psi(h^{-1}x)$, we obtain the refinement of the bad constant $|\phi|_\infty^2$ into a constant that behaves like $|\phi|_{L^1(\text{Leb})} |\phi|_\infty$.

Definition

A bifurcating Markov chain is a family $(X_u)_{u \in \mathbb{T}}$ of random variables with value in $(\mathcal{S}, \mathfrak{G})$ such that X_u is $\mathcal{F}_{|u|}$ -measurable for every $u \in \mathbb{T}$ and

$$\mathbb{E} \left[\prod_{u \in \mathbb{G}_m} g_u(X_u, X_{u0}, X_{u1}) \middle| \mathcal{F}_m \right] = \prod_{u \in \mathbb{G}_m} \mathcal{P}g_u(X_u)$$

for every $m \geq 0$ and $(g_u)_{u \in \mathbb{G}_m}$, where

$$\mathcal{P}g(x) = \int_{\mathcal{S} \times \mathcal{S}} g(x, y, z) \mathcal{P}(x, dy dz)$$

Essential object: the mean transition

- ▶ The tagged-branch chain $(Y_m)_{m \geq 0}$: $Y_0 = X_\emptyset$ and for $m \geq 1$,

$$Y_m = X_{\emptyset \epsilon_1 \dots \epsilon_m},$$

$(\epsilon_m)_{m \geq 1}$ IID Bernoulli with parameter $1/2$, independent of $(X_u)_{u \in \mathbb{T}}$.

- ▶ Transition (mean transition)

$$Q = (\mathcal{P}_0 + \mathcal{P}_1) / 2,$$

obtained from the marginals $\mathcal{P}_0(x, dy) = \int_{z \in \mathcal{S}} \mathcal{P}(x, dy dz)$
and $\mathcal{P}_1(x, dz) = \int_{y \in \mathcal{S}} \mathcal{P}(x, dy dz)$.

Digest

- ▶ Guyon (2007) proves that if $(Y_m)_{m \geq 0}$ is ergodic with invariant measure ν , then

$$\frac{1}{|\mathbb{G}_n|} \sum_{u \in \mathbb{G}_n} g(X_u) \rightarrow \int_S g(x) \nu(dx)$$

holds almost-surely as $n \rightarrow \infty$.

- ▶ We also have

$$\frac{1}{|\mathbb{T}_n|} \sum_{u \in \mathbb{T}_n} g(X_u, X_{u0}, X_{u1}) \rightarrow \int_S \mathcal{P}g(x) \nu(dx)$$

almost-surely as $n \rightarrow \infty$.

- ▶ These results are appended with central limit theorems.

Toward statistical inference

- ▶ $\mathcal{D} \subseteq \mathcal{S}$ that will be later needed for statistical purposes.
- ▶ Mean transition $Q = \frac{1}{2}(\mathcal{P}_0 + \mathcal{P}_1)$.

Assumptions

- ▶ **Assumption (D)** The family $\{Q(x, dy), x \in \mathcal{S}\}$ is dominated:

$$Q(x, dy) = Q(x, y)n(dy) \text{ for every } x \in \mathcal{S},$$

for some $Q : \mathcal{S}^2 \rightarrow [0, \infty)$ such that

$$|Q|_{\mathcal{D}} = \sup_{x \in \mathcal{S}, y \in \mathcal{D}} Q(x, y) < \infty.$$

- ▶ **Assumption (UE)** Q admits a unique invariant probability measure ν and there exist $R > 0$ and $0 < \rho < 1/2$ such that

$$|Q^m g(x) - \nu(g)| \leq R|g|_{\infty} \rho^m, \quad x \in \mathcal{S}, \quad m \geq 0,$$

Variance definitions

- ▶ For $g : \mathcal{S}^d \rightarrow \mathbb{R}$, define $\Sigma_{1,1}(g) = |g|_2^2$ and for $n \geq 2$,

$$\Sigma_{1,n}(g) = |g|_2^2 + \min_{1 \leq \ell \leq n-1} (|g|_1^2 2^\ell + |g|_\infty^2 2^{-\ell}). \quad (1)$$

- ▶ Define also $\Sigma_{2,1}(g) = |\mathcal{P}g^2|_1$ and for $n \geq 2$,

$$\Sigma_{2,n}(g) = |\mathcal{P}g^2|_1 + \min_{1 \leq \ell \leq n-1} (|\mathcal{P}g|_1^2 2^\ell + |\mathcal{P}g|_\infty^2 2^{-\ell}). \quad (2)$$

One-step deviations

Theorem

Under **(D)** and **(UE)**, for every $n \geq 1$:

(i) For any $\delta > 0$ such that $\delta \geq 4R|g|_\infty|\mathbb{G}_n|^{-1}$, we have

$$\mathbb{P}\left(\frac{1}{|\mathbb{G}_n|} \sum_{u \in \mathbb{G}_n} g(X_u) - \nu(g) \geq \delta\right) \leq \exp\left(\frac{-|\mathbb{G}_n|\delta^2}{\kappa_1 \Sigma_{1,n}(g) + \kappa_2 |g|_\infty \delta}\right).$$

(ii) For any $\delta > 0$ such that $\delta \geq 4R(1 - 2\rho)^{-1}|g|_\infty|\mathbb{T}_n|^{-1}$, we have

$$\mathbb{P}\left(\frac{1}{|\mathbb{T}_n|} \sum_{u \in \mathbb{T}_n} g(X_u) - \nu(g) \geq \delta\right) \leq \exp\left(\frac{-|\mathbb{T}_n|\delta^2}{\kappa_3 \Sigma_{1,n}(g) + \kappa_4 |g|_\infty \delta}\right).$$

Two-steps deviations

Theorem

Under **(D)** and **(UE)**, for every $n \geq 2$:

(i) For any $\delta > 0$ such that $\delta \geq 4R|\mathcal{P}g|_\infty|\mathbb{G}_n|^{-1}$, we have

$$\mathbb{P}\left(\frac{1}{|\mathbb{G}_n|} \sum_{u \in \mathbb{G}_n} g(X_u, X_{u0}, X_{u1}) - \nu(\mathcal{P}g) \geq \delta\right) \leq \exp\left(\frac{-|\mathbb{G}_n|\delta^2}{\kappa_1 \Sigma_{2,n}(g) + \kappa_2 |g|_\infty \delta}\right)$$

(ii) For any $\delta > 0$ such that $\delta \geq 4(nR|\mathcal{P}g|_\infty + |g|_\infty)|\mathbb{T}_{n-1}|^{-1}$, we have

$$\begin{aligned} & \mathbb{P}\left(\frac{1}{|\mathbb{T}_{n-1}|} \sum_{u \in \mathbb{T}_{n-1}} g(X_u, X_{u0}, X_{u1}) - \nu(\mathcal{P}g) \geq \delta\right) \\ & \leq \exp\left(\frac{-n^{-1}|\mathbb{T}_{n-1}|\delta^2}{\kappa_1 \Sigma_{2,n-1}(g) + \kappa_2 |g|_\infty \delta}\right). \end{aligned}$$

Statistical inference

- ▶ From now on $(\mathcal{S}, \mathfrak{G}) = (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ and $\mathcal{D} \subset \mathcal{S}$ compact interval
- ▶ **Assumption (S)** The family $\{\mathcal{P}(x, dy dz), x \in \mathcal{S}\}$ is dominated w.r.t. the Lebesgue measure:

$$\mathcal{P}(x, dy dz) = \mathcal{P}(x, y, z) dy dz \text{ for every } x \in \mathcal{S}$$

for some $\mathcal{P} : \mathcal{S}^3 \rightarrow [0, \infty)$ such that

$$|\mathcal{P}|_{\mathcal{D}} = \sup_{(x,y,z) \in \mathcal{D}^3} |\mathcal{P}(x, y, z)| < \infty.$$

Statistical inference (cont.)

- ▶ For some $n \geq 1$, we observe $(X_u)_{u \in \mathbb{T}_n}$
- ▶ Under **(D)**, **(S)**, with $\mathfrak{n}(dy) = dy$, we have
 - ▶ $\mathcal{P}(x, dy dz) = \mathcal{P}(x, y, z) dy dz$
 - ▶ $\mathcal{Q}(x, dy) = \mathcal{Q}(x, y) dy$
 - ▶ $\nu(dx) = \nu(x) dx$
- ▶ Goal: estimate nonparametrically $x \rightsquigarrow \nu(x)$, $(x, y) \rightsquigarrow \mathcal{Q}(x, y)$ and $(x, y, z) \rightsquigarrow \mathcal{P}(x, y, z)$ for $x, y, z \in \mathcal{D}$.

Nonparametric estimation of $\nu(x)$

- ▶ For a σ -regular wavelet basis, we approximate the representation

$$\nu(x) = \sum_{\lambda \in \Lambda} \nu_\lambda \psi_\lambda^1(x), \quad \nu_\lambda = \langle \nu, \psi_\lambda^1 \rangle$$

by

$$\hat{\nu}_n(x) = \sum_{|\lambda| \leq J} \hat{\nu}_{\lambda,n} \psi_\lambda^1(x),$$

with

$$\hat{\nu}_{\lambda,n} = \mathcal{T}_{\lambda,\eta} \left(\frac{1}{|\mathbb{T}_n|} \sum_{u \in \mathbb{T}_n} \psi_\lambda^1(X_u) \right).$$

- ▶ $\mathcal{T}_{\lambda,\eta}(x) = x \mathbf{1}_{|x| \geq \eta}$ threshold operator (with $\mathcal{T}_{\lambda,\eta}(x) = x$ for the low frequency part).
- ▶ $\hat{\nu}_n$ is specified by the maximal resolution level J and the threshold η .

Theorem

Under **(D)** and **(UE)** with $n(dx) = dx$, specify $\hat{\nu}_n$ with

$$J = \log_2 \frac{|\mathbb{T}_n|}{\log |\mathbb{T}_n|} \quad \text{and} \quad \eta = c \sqrt{\log |\mathbb{T}_n| / |\mathbb{T}_n|}$$

for some $c > 0$. For every $\pi \in (0, \infty]$, $s \in (1/\pi, \sigma]$ and $p \geq 1$, for large enough n and c , the following estimate holds

$$\left(\mathbb{E} \left[\|\hat{\nu}_n - \nu\|_{L^p(\mathcal{D})}^p \right] \right)^{1/p} \lesssim \left(\frac{\log |\mathbb{T}_n|}{|\mathbb{T}_n|} \right)^{\alpha_1(s, p, \pi)},$$

with $\alpha_1(s, p, \pi) = \min \left\{ \frac{s}{2s+1}, \frac{s+1/p-1/\pi}{2s+1-2/\pi} \right\}$, up to a constant that depends on $s, p, \pi, \|\nu\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D})}, \rho, R$ and $|\mathcal{Q}|_{\mathcal{D}}$ and that is continuous in its arguments.

- ▶ The estimator $\hat{\nu}_n$ is *smooth-adaptive* in the following sense: for every $s_0 > 0$, $0 < \rho_0 < 1/2$, $R_0 > 0$ and $Q_0 > 0$, define the sets $\mathcal{A}(s_0) = \{(s, \pi), s \geq s_0, s_0 \geq 1/\pi\}$ and

$$\mathcal{Q}(\rho_0, R_0, Q_0) = \{Q \text{ such that } \rho \leq \rho_0, R \leq R_0, |Q|_{\mathcal{D}} \leq Q_0\},$$

where Q is taken among mean transitions for which **(UE)**

holds. Then, for every $C > 0$, there exists

$c^* = c^*(\mathcal{D}, \rho, s_0, \rho_0, R_0, Q_0, C)$ such that $\hat{\nu}_n$ specified with c^* satisfies

$$\sup_n \sup_{(s, \pi) \in \mathcal{A}(s_0)} \sup_{\nu, Q} \left(\frac{|\mathbb{T}_n|}{\log |\mathbb{T}_n|} \right)^{\rho \alpha_1(s, \rho, \pi)} \mathbb{E} [\|\hat{\nu}_n - \nu\|_{L^p(\mathcal{D})}^p] < \infty$$

where the supremum is taken among (ν, Q) such that $\nu Q = \nu$ with $Q \in \mathcal{Q}(\rho_0, R_0, Q_0)$ and $\|\nu\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D})} \leq C$.

Nonparametric estimation of the mean transition $Q(x, y)$

- ▶ First estimate

$$f_Q(x, y) = \nu(x)Q(x, y)$$

of the distribution of (X_{u-}, X_u) (when $\mathcal{L}(X_\emptyset) = \nu$) by

$$\hat{f}_n(x, y) = \sum_{|\lambda| \leq J} \hat{f}_{\lambda, n} \psi_\lambda^2(x, y),$$

with

$$\hat{f}_{\lambda, n} = \mathcal{T}_{\lambda, \eta} \left(\frac{1}{|\mathbb{T}_n^*|} \sum_{u \in \mathbb{T}_n^*} \psi_\lambda^2(X_{u-}, X_u) \right),$$

($\mathbb{T}_n^* = \mathbb{T}_n \setminus \mathbb{G}_0$.)

- ▶ Estimate $Q(x, y)$ via

$$\hat{Q}_n(x, y) = \frac{\hat{f}_n(x, y)}{\max\{\hat{\nu}_n(x), \varpi\}} \quad (3)$$

for some $\varpi > 0$.

- ▶ Thus \hat{Q}_n is specified by J , η and ϖ .

Theorem

Under **(D)** and **(UE)** with $n(dx) = dx$, specify \widehat{Q}_n with

$$J = \frac{1}{2} \log_2 \frac{|\mathbb{T}_n|}{\log |\mathbb{T}_n|} \quad \text{and} \quad \eta = c \sqrt{(\log |\mathbb{T}_n|)^2 / |\mathbb{T}_n|}$$

for some $c > 0$ and $\varpi > 0$. For every $\pi \in [1, \infty]$, $s \in (2/\pi, \sigma]$ and $p \geq 1$, for large enough n and c and small enough ϖ , the following estimate holds

$$\left(\mathbb{E} \left[\left\| \widehat{Q}_n - Q \right\|_{L^p(\mathcal{D}^2)}^p \right] \right)^{1/p} \lesssim \left(\frac{(\log |\mathbb{T}_n|)^2}{|\mathbb{T}_n|} \right)^{\alpha_2(s, p, \pi)}, \quad (4)$$

with $\alpha_2(s, p, \pi) = \min \left\{ \frac{s}{2s+2}, \frac{s/2+1/p-1/\pi}{s+1-2/\pi} \right\}$, provided $m(\nu) = \inf_{x \in \mathcal{D}} \nu(x) \geq \varpi > 0$ and up to a constant that depends on $s, p, \pi, \|Q\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D}^2)}$, $m(\nu)$ and that is continuous in its arguments.

- ▶ This rate is moreover (nearly) optimal: define $\varepsilon_2 = s\pi - (p - \pi)$. We have

$$\inf_{\hat{Q}_n} \sup_Q \left(\mathbb{E} \left[\|\hat{Q}_n - Q\|_{L^p(\mathcal{D}^2)}^p \right] \right)^{1/p} \gtrsim \begin{cases} |\mathbb{T}_n|^{-\alpha_2(s,p,\pi)} & \text{if } \varepsilon_2 > 0 \\ \left(\frac{\log |\mathbb{T}_n|}{|\mathbb{T}_n|} \right)^{\alpha_2(s,p,\pi)} & \text{if } \varepsilon_2 \leq 0 \end{cases}$$

where the infimum is taken among all estimators of Q based on $(X_u)_{u \in \mathbb{T}_n}$ and the supremum is taken among all Q such that $\|Q\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D}^2)} \leq C$ and $m(\nu) \geq C'$ for some $C, C' > 0$.

- ▶ The calibration of the threshold ϖ needed to define \hat{Q}_n requires an *a priori* bound on $m(\nu)$.
- ▶ The $(\log |\mathbb{T}_n|)^2$ comes from the slow term in the deviations inequality and from the wavelet thresholding procedure.

Nonparametric estimation of the transition $\mathcal{P}(x, y, z)$

- ▶ First estimate the density

$$f_{\mathcal{P}}(x, y, z) = \nu(x)\mathcal{P}(x, y, z)$$

of the distribution of (X_u, X_{u0}, X_{u1}) (when $\mathcal{L}(X_\emptyset) = \nu$) by

$$\hat{f}_n(x, y, z) = \sum_{|\lambda| \leq J} \hat{f}_{\lambda, n} \psi_\lambda^3(x, y, z),$$

with

$$\hat{f}_{\lambda, n} = \mathcal{T}_{\lambda, \eta} \left(\frac{1}{|\mathbb{T}_{n-1}|} \sum_{u \in \mathbb{T}_{n-1}} \psi_\lambda^3(X_u, X_{u0}, X_{u1}) \right),$$

- ▶ Next estimate the density \mathcal{P} by

$$\hat{\mathcal{P}}_n(x, y, z) = \frac{\hat{f}_n(x, y, z)}{\max\{\hat{\nu}_n(x), \varpi\}} \quad (5)$$

for some threshold $\varpi > 0$.

- ▶ Thus the estimator $\hat{\mathcal{P}}_n$ is specified by J , η and ϖ .

Theorem

Under **(D)**, **(UE)**, **(S)**. Specify $\widehat{\mathcal{P}}_n$ with

$$J = \frac{1}{3} \log_2 \frac{|\mathbb{T}_n|}{\log |\mathbb{T}_n|} \quad \text{and} \quad \eta = c \sqrt{(\log |\mathbb{T}_n|)^2 / |\mathbb{T}_n|}$$

for some $c > 0$ and $\varpi > 0$. For every $\pi \in [1, \infty]$, $s \in (3/\pi, \sigma]$ and $p \geq 1$, for large enough n and c and small enough ϖ , the following estimate holds

$$\left(\mathbb{E} \left[\left\| \widehat{\mathcal{P}}_n - \mathcal{P} \right\|_{L^p(\mathcal{D}^3)}^p \right] \right)^{1/p} \lesssim \left(\frac{(\log |\mathbb{T}_n|)^2}{|\mathbb{T}_n|} \right)^{\alpha_3(s, p, \pi)}, \quad (6)$$

with $\alpha_3(s, p, \pi) = \min \left\{ \frac{s}{2s+3}, \frac{s/3+1/p-1/\pi}{2s/3+1-2/\pi} \right\}$, provided $m(\nu) \geq \varpi > 0$ and up to a constant that depends on $s, p, \pi, \|\mathcal{P}\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D}^3)}$ and $m(\nu)$ and that is continuous in its arguments.

- ▶ This rate is moreover (nearly) optimal: define $\varepsilon_3 = \frac{s\pi}{3} - \frac{\rho-\pi}{2}$.
We have

$$\inf_{\widehat{\mathcal{P}}_n} \sup_{\mathcal{P}} \left(\mathbb{E} \left[\|\widehat{\mathcal{P}}_n - \mathcal{P}\|_{L^p(\mathcal{D}^3)}^p \right] \right)^{1/p} \gtrsim \begin{cases} |\mathbb{T}_n|^{-\alpha_3(s,\rho,\pi)} & \text{if } \varepsilon_3 > 0 \\ \left(\frac{\log |\mathbb{T}_n|}{|\mathbb{T}_n|} \right)^{\alpha_3(s,\rho,\pi)} & \text{if } \varepsilon_3 \leq 0, \end{cases}$$

where the infimum is taken among all estimators of \mathcal{P} based on $(X_u)_{u \in \mathbb{T}_n}$ and the supremum is taken among all \mathcal{P} such that $\|\mathcal{P}\|_{\mathcal{B}_{\pi,\infty}^s(\mathcal{D}^3)} \leq C$ and $m(\nu) \geq C'$ for some $C, C' > 0$.

Application: cell division by growth

- ▶ To each node (or cell) $u \in \mathbb{T}$, we associate as trait $X_u \in \mathcal{S} \subset (0, \infty)$ the size at birth of the cell u .
- ▶ Each cell grows exponentially with a common rate $\tau > 0$.
- ▶ A cell of size x splits into two newborn cells of size $x/2$ each (thus $X_{u0} = X_{u1}$ here), with a size-dependent splitting rate $B(x)$ for some $B : \mathcal{S} \rightarrow [0, \infty)$.
- ▶ Two newborn cells start a new life independently of each other.

- ▶ If ζ_u denotes the lifetime of the cell u , we thus have

$$\mathbb{P}(\zeta_u \in [t, t + dt) | \zeta_u \geq t, X_u = x) = B(x \exp(\tau t)) dt$$

and

$$X_u = \frac{1}{2} X_{u-} \exp(\tau \zeta_{u-})$$

that entirely determine the evolution of the population.

- ▶ Goal: estimate $x \rightsquigarrow B(x)$ for $x \in \mathcal{D}$ where $\mathcal{D} \subset \mathcal{S}$ is a given compact interval.

- ▶ The process $(X_u)_{u \in \mathbb{T}}$ is a bifurcating Markov chain with state space \mathcal{S} and \mathbb{T} -transition

$$\mathcal{P}_B(x, dy dz) = \mathbb{P}(X_{u0} \in dy, X_{u1} \in dz | X_{u-} = x).$$

- ▶ it is not difficult to check that

$$\mathcal{P}_B(x, dy dz) = Q_B(x, dy) \otimes \delta_y(dz)$$

and

$$Q_B(x, dy) = \frac{B(2y)}{\tau y} \exp\left(-\int_{x/2}^y \frac{B(2s)}{\tau s} ds\right) \mathbf{1}_{\{y \geq x/2\}} dy.$$

- ▶ $x \rightsquigarrow B(x)$ is continuous implies **(D)** with $\mathcal{Q} = Q_B$ and $n(dx) = dx$.
- ▶ Let $\mathcal{S} = (0, C]$. Pick $r \in \mathcal{S}$ and $L > 0$ and let

$$\mathcal{C}(r, L) = \left\{ B, \int^{\sup \mathcal{S}} \frac{B(x)}{x} dx = \infty, \int_0^r \frac{B(x)}{x} dx \leq L \right\}.$$

- ▶ We comply with **(UE)** for $\mathcal{Q} = Q_B$ with $0 < \rho < 1/2$ if $r > \sup \mathcal{S}/2$ and $0 < L < \tau \log 2$.
- ▶ We know by Proposition 2 in Doumic *et al.* (2015) that

$$B(x) = \frac{\tau x}{2} \frac{\nu_B(x/2)}{\int_{x/2}^x \nu_B(z) dz},$$

where ν_B denotes the unique invariant probability of the transition $\mathcal{Q} = Q_B$.

- ▶ For a given compact interval $\mathcal{D} \subset \mathcal{S}$, define

$$\widehat{B}_n(x) = \frac{\tau x}{2} \frac{\widehat{\nu}_n(x/2)}{\left(\frac{1}{|\mathbb{T}_n|} \sum_{u \in \mathbb{T}_n} \mathbf{1}_{\{x/2 \leq X_u < x\}}\right) \vee \varpi}, \quad (7)$$

where $\widehat{\nu}_n$ is the wavelet thresholding estimator specified by a maximal resolution level J and a threshold η and $\varpi > 0$

Theorem

Specify \widehat{B}_n with

$$J = \frac{1}{2} \log_2 \frac{|\mathbb{T}_n|}{\log |\mathbb{T}_n|} \quad \text{and} \quad \eta = c \sqrt{\log |\mathbb{T}_n| / |\mathbb{T}_n|}$$

for some $c > 0$. For every $B \in \mathcal{C}(r, L)$, for every $\pi \in (0, \infty]$, $s \in (1/\pi, \sigma]$ and $p \geq 1$, for large enough n and c and small enough ϖ , the following estimate holds

$$\left(\mathbb{E} \left[\|\widehat{B}_n - B\|_{L^p(\mathcal{D})}^p \right] \right)^{1/p} \lesssim \left(\frac{\log |\mathbb{T}_n|}{|\mathbb{T}_n|} \right)^{\alpha_1(s, p, \pi)},$$

provided that $\inf \mathcal{D} \leq r/2$, with

$\alpha_1(s, p, \pi) = \min \left\{ \frac{2s}{2s+1}, \frac{s+1/p-1/\pi}{2s+1-2/\pi} \right\}$, up to a constant that depends on $s, p, \pi, \|B\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D})}, r$ and L and that is continuous in its arguments.

- ▶ This rate is moreover (nearly) optimal: define $\varepsilon_1 = s\pi - \frac{1}{2}(p - \pi)$. We have

$$\inf_{\widehat{B}_n} \sup_B \left(\mathbb{E} \left[\|\widehat{B}_n - B\|_{L^p(\mathcal{D})}^p \right] \right)^{1/p} \gtrsim \begin{cases} |\mathbb{T}_n|^{-\alpha_1(s,p,\pi)} & \text{if } \varepsilon_1 > 0 \\ \left(\frac{\log |\mathbb{T}_n|}{|\mathbb{T}_n|} \right)^{\alpha_1(s,p,\pi)} & \text{if } \varepsilon_1 \leq 0, \end{cases}$$

where the infimum is taken among all estimators of B based on $(X_u)_{u \in \mathbb{T}_n}$ and the supremum is taken among all $B \in \mathcal{C}(r, L)$ such that $\|B\|_{\mathcal{B}_{\pi, \infty}^s(\mathcal{D})} \leq C$.

- ▶ We improve on the results of Doumic *et al.* in two directions: smoothness adaptation + minimax results
- ▶ Quite stringent restriction that \mathcal{S} is bounded

- ▶ We consider a perturbation of the baseline splitting rate $\tilde{B}(x) = x/(5 - x)$ over the range $x \in \mathcal{S} = (0, 5)$ of the form

$$B(x) = \tilde{B}(x) + c T(2^j(x - \frac{7}{2}))$$

with $(c, j) = (3, 1)$ or $(c, j) = (9, 4)$, and where

$T(x) = (1 + x)\mathbf{1}_{\{-1 \leq x < 0\}} + (1 - x)\mathbf{1}_{\{0 \leq x \leq 1\}}$ is a tent shaped function.

- ▶ the trial splitting rate with parameter $(c, j) = (9, 4)$ is more localized around $7/2$ and higher than the one associated with parameter $(c, j) = (3, 1)$.
- ▶ For a given B , we simulate $M = 100$ Monte Carlo trees up to the generation $n = 15$ with $\tau = 2$.

Numerical illustration

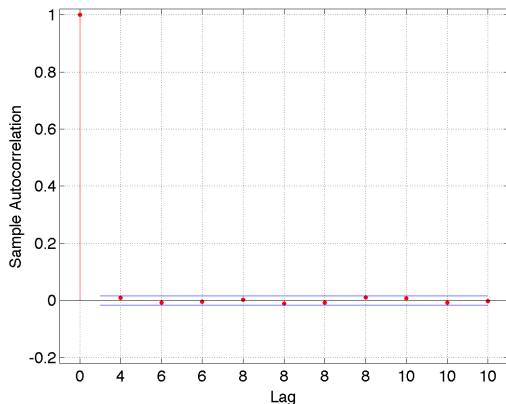


Figure : *Sample autocorrelation of ordered $(X_{u0}, u \in \mathbb{G}_{n-1})$ for $n = 15$. Note: due to the binary tree structure the lags are $\{4, 6, 6, \dots\}$. As expected, we observe a fast decorrelation.*

- ▶ We implement the estimator \widehat{B}_n defined by (7) using the Matlab wavelet toolbox.
- ▶ We use compactly supported Daubechies wavelets of order 8. $J := \frac{1}{2} \log_2(|\mathbb{T}_n| / \log |\mathbb{T}_n|)$ and we threshold the coefficients $\widehat{\nu}_{\lambda,n}$ which are too small by hard thresholding.
- ▶ We choose the threshold proportional to $\sqrt{\log |\mathbb{T}_n| / |\mathbb{T}_n|}$ (and we calibrate the constant to 10 or 15 for respectively the two trial splitting rates, mainly by visual inspection).
- ▶ We evaluate \widehat{B}_n on a regular grid of $\mathcal{D} = [1.5, 4.8]$ with mesh $\Delta x = (|\mathbb{T}_n|)^{-1/2}$. For each sample we compute the empirical error

$$e_i = \frac{\|\widehat{B}_n^{(i)} - B\|_{\Delta x}}{\|B\|_{\Delta x}}, \quad i = 1, \dots, M,$$

where $\|\cdot\|_{\Delta x}$ denotes the discrete L^2 -norm over the numerical sampling and sum up the results through the mean-empirical error $\bar{e} = M^{-1} \sum_{i=1}^M e_i$, together with the empirical standard deviation $(M^{-1} \sum_{i=1}^M (e_i - \bar{e})^2)^{1/2}$.

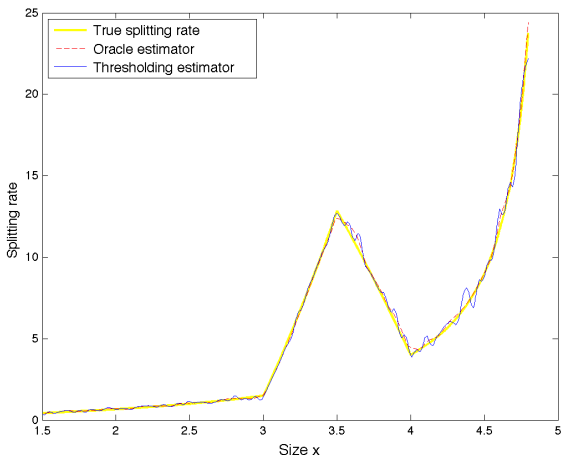


Figure : *Large spike: reconstruction of the trial splitting rate B specified by $(c, j) = (3, 1)$ over $\mathcal{D} = [1.5, 4.8]$ based on one sample $(X_u, u \in \mathbb{T}_n)$ for $n = 15$ (i.e. $\frac{1}{2}|\mathbb{T}_n| = 32\,767$).*

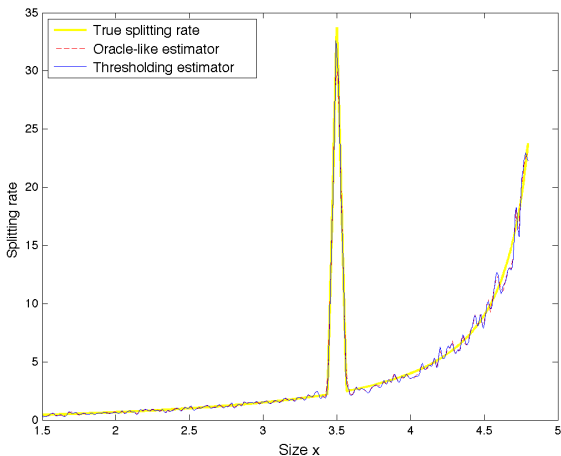


Figure : High spike: reconstruction of the trial splitting rate B specified by $(c, j) = (9, 4)$ over $\mathcal{D} = [1.5, 4.8]$ based on one sample $(X_u, u \in \mathbb{T}_n)$ for $n = 15$ (i.e. $\frac{1}{2}|\mathbb{T}_n| = 32\,767$).

THANK YOU FOR YOUR ATTENTION!