### Inverse problems for boundary triples with applications

Malcolm Brown

Cardiff University

June 2017

joint work with M. Marletta (Cardiff), S. Naboko (St. Petersburg) and Ian Wood (Kent)

• Titchmarsh-Weyl m-function for Sturm-Liouville problems

- Titchmarsh-Weyl m-function for Sturm-Liouville problems
- Dirichlet-to-Neumann map

- Titchmarsh-Weyl m-function for Sturm-Liouville problems
- Dirichlet-to-Neumann map

Aims:

- look at how this notions can be discussed for more general operators
- what can be said about the operator from boundary date
- extend results to non-selfadjoint operators as far as possible

- Titchmarsh-Weyl m-function for Sturm-Liouville problems
- Dirichlet-to-Neumann map

Aims:

- look at how this notions can be discussed for more general operators
- what can be said about the operator from boundary date
- extend results to non-selfadjoint operators as far as possible

Method: make use of abstract theory of boundary triples to

- introduce *M*-function,
- relate resolvent to operators on the boundary,

A and A closed, densely defined operators on Hilbert space H
A ⊆ (A)\* =: A<sub>max</sub> and A ⊆ A\* =: A<sub>max</sub>

- A and  $\widetilde{A}$  closed, densely defined operators on Hilbert space H
- $A \subseteq (\widetilde{A})^* =: A_{\max}$  and  $\widetilde{A} \subseteq A^* =: \widetilde{A}_{\max}$
- $\bullet$  there exist "boundary spaces"  $\mathcal H,\,\mathcal K$  and "boundary operators",

• 
$$\Gamma_1: D(A_{\max}) \to \mathcal{H}$$
 and  $\Gamma_0: D(A_{\max}) \to \mathcal{K}$ ,

• 
$$\widetilde{\Gamma}_1: D(\widetilde{A}_{\max}) \to \mathcal{K}$$
 and  $\widetilde{\Gamma}_0: D(\widetilde{A}_{\max}) \to \mathcal{H}$ ,

which are bounded in graph norm,  $(\Gamma_1, \Gamma_0), (\widetilde{\Gamma}_1, \widetilde{\Gamma}_0)$  are surjective,

- A and  $\widetilde{A}$  closed, densely defined operators on Hilbert space H
- $A \subseteq (\widetilde{A})^* =: A_{\max}$  and  $\widetilde{A} \subseteq A^* =: \widetilde{A}_{\max}$
- $\bullet$  there exist "boundary spaces"  $\mathcal H,\,\mathcal K$  and "boundary operators",

• 
$$\Gamma_1: D(A_{\max}) \to \mathcal{H}$$
 and  $\Gamma_0: D(A_{\max}) \to \mathcal{K}$ ,  
•  $\widetilde{\Gamma}_1: D(\widetilde{A}_{\max}) \to \mathcal{K}$  and  $\widetilde{\Gamma}_0: D(\widetilde{A}_{\max}) \to \mathcal{H}$ ,

which are bounded in graph norm,  $(\Gamma_1, \Gamma_0), (\widetilde{\Gamma}_1, \widetilde{\Gamma}_0)$  are surjective, and such that for  $u \in D(A_{\max})$  and  $v \in D(\widetilde{A}_{\max})$  we have

$$(A_{\max}u,v)_{\mathcal{H}}-(u,\widetilde{A}_{\max}v)_{\mathcal{H}}=(\Gamma_{1}u,\widetilde{\Gamma}_{0}v)_{\mathcal{H}}-(\Gamma_{0}u,\widetilde{\Gamma}_{1}v)_{\mathcal{K}}.$$

- A and  $\widetilde{A}$  closed, densely defined operators on Hilbert space H
- $A \subseteq (\widetilde{A})^* =: A_{\max}$  and  $\widetilde{A} \subseteq A^* =: \widetilde{A}_{\max}$
- $\bullet$  there exist "boundary spaces"  $\mathcal H,\,\mathcal K$  and "boundary operators",

• 
$$\Gamma_1: D(A_{\max}) \to \mathcal{H}$$
 and  $\Gamma_0: D(A_{\max}) \to \mathcal{K}$ ,  
•  $\widetilde{\Gamma}_1: D(\widetilde{A}_{\max}) \to \mathcal{K}$  and  $\widetilde{\Gamma}_0: D(\widetilde{A}_{\max}) \to \mathcal{H}$ ,

which are bounded in graph norm,  $(\Gamma_1, \Gamma_0), (\widetilde{\Gamma}_1, \widetilde{\Gamma}_0)$  are surjective, and such that for  $u \in D(A_{\max})$  and  $v \in D(\widetilde{A}_{\max})$  we have

$$(A_{\max}u,v)_{\mathcal{H}}-(u,\widetilde{A}_{\max}v)_{\mathcal{H}}=(\Gamma_{1}u,\widetilde{\Gamma}_{0}v)_{\mathcal{H}}-(\Gamma_{0}u,\widetilde{\Gamma}_{1}v)_{\mathcal{K}}.$$

 $\{\mathcal{H} \oplus \mathcal{K}, (\Gamma_1, \Gamma_0), (\widetilde{\Gamma}_1, \widetilde{\Gamma}_0)\}$  is a boundary triple for the adjoint pair  $A, \widetilde{A}$ .

# **ODE** Example

For  $p \in C^1(0,1)$ , p > 0,  $q \in L^\infty(0,1)$ , consider

$$Lu = \left(-\frac{d}{dx}p\frac{d}{dx} + q\right)u$$
 and  $\widetilde{L}u = \left(-\frac{d}{dx}p\frac{d}{dx} + \overline{q}\right)u$  on  $(0, 1)$ .

Let Au = Lu and  $\widetilde{A}u = \widetilde{L}u$  with  $D(A) = D(\widetilde{A}) = H_0^2(0, 1)$ .

# **ODE** Example

For  $p \in C^1(0,1)$ , p > 0,  $q \in L^{\infty}(0,1)$ , consider

$$Lu = \left(-\frac{d}{dx}p\frac{d}{dx} + q\right)u$$
 and  $\widetilde{L}u = \left(-\frac{d}{dx}p\frac{d}{dx} + \overline{q}\right)u$  on  $(0, 1)$ .

Let Au = Lu and  $\widetilde{A}u = \widetilde{L}u$  with  $D(A) = D(\widetilde{A}) = H_0^2(0, 1)$ . Then

 $A_{\max}u = Lu, \quad \widetilde{A}_{\max}u = \widetilde{L}u \quad \text{with} \quad D(A_{\max}) = D(\widetilde{A}_{\max}) = H^2(0,1).$ 

# ODE Example

For  $p \in C^1(0,1)$ , p > 0,  $q \in L^{\infty}(0,1)$ , consider

$$Lu = \left(-\frac{d}{dx}p\frac{d}{dx} + q\right)u$$
 and  $\widetilde{L}u = \left(-\frac{d}{dx}p\frac{d}{dx} + \overline{q}\right)u$  on  $(0, 1)$ .

Let Au = Lu and  $\widetilde{A}u = \widetilde{L}u$  with  $D(A) = D(\widetilde{A}) = H_0^2(0, 1)$ . Then

 $A_{\max}u = Lu$ ,  $\widetilde{A}_{\max}u = \widetilde{L}u$  with  $D(A_{\max}) = D(\widetilde{A}_{\max}) = H^2(0, 1)$ . For  $u, v \in H^2(0, 1)$ 

$$\left\langle A_{\max}u,v\right\rangle_{L^{2}}-\left\langle u,\widetilde{A}_{\max}v\right\rangle_{L^{2}} = \left\langle \Gamma_{1}u,\widetilde{\Gamma}_{0}v\right\rangle_{\mathbb{C}^{2}}-\left\langle \Gamma_{0}u,\widetilde{\Gamma}_{1}v\right\rangle_{\mathbb{C}^{2}},$$

where

$$\Gamma_1 u = \widetilde{\Gamma}_1 u = \begin{pmatrix} -p(1)u'(1) \\ p(0)u'(0) \end{pmatrix}, \quad \Gamma_0 u = \widetilde{\Gamma}_0 u = \begin{pmatrix} u(1) \\ u(0) \end{pmatrix}$$

and  $\mathcal{H} = \mathcal{K} = \mathbb{C}^2$ .

Malcolm Brown (Cardiff)

•  $B \in \mathcal{L}(\mathcal{K}, \mathcal{H})$  and  $A_B := A_{\max}|_{\ker(\Gamma_1 - B\Gamma_0)}$ ,

• 
$$B \in \mathcal{L}(\mathcal{K}, \mathcal{H})$$
 and  $A_B := A_{\max}|_{\ker(\Gamma_1 - B\Gamma_0)}$ ,

• for  $\lambda \in \rho(A_B)$  define the solution operator as a mapping

$$\mathcal{S}_{\lambda,B}:\mathcal{H}
ightarrow \mathsf{ker}(\mathcal{A}_{\mathrm{max}}-\lambda)$$

where  $u = S_{\lambda,B} f$  solves

$$(A_{\max} - \lambda)u = 0, \ (\Gamma_1 - B\Gamma_0)u = f,$$

• 
$$B \in \mathcal{L}(\mathcal{K}, \mathcal{H})$$
 and  $A_B := A_{\max}|_{\ker(\Gamma_1 - B\Gamma_0)}$ ,

• for  $\lambda \in \rho(A_B)$  define the solution operator as a mapping

$$S_{\lambda,B}: \mathcal{H} o \ker(A_{\max} - \lambda))$$

where  $u = S_{\lambda,B} f$  solves

$$(A_{\max} - \lambda)u = 0, \ (\Gamma_1 - B\Gamma_0)u = f,$$

• for  $\lambda \in \rho(A_B)$  define the *M*-function via

$$M_B(\lambda): \mathcal{H} \to \mathcal{K}, \quad M_B(\lambda)f = \Gamma_0 S_{\lambda,B}f.$$

• 
$$B \in \mathcal{L}(\mathcal{K}, \mathcal{H})$$
 and  $A_B := A_{\max}|_{\ker(\Gamma_1 - B\Gamma_0)}$ ,

• for  $\lambda \in \rho(A_B)$  define the solution operator as a mapping

$$\mathcal{S}_{\lambda,B}:\mathcal{H}
ightarrow \mathsf{ker}(\mathcal{A}_{\mathrm{max}}-\lambda)$$

where  $u = S_{\lambda,B} f$  solves

$$(A_{\max} - \lambda)u = 0, \ (\Gamma_1 - B\Gamma_0)u = f,$$

• for  $\lambda \in \rho(A_B)$  define the *M*-function via

$$M_B(\lambda): \mathcal{H} \to \mathcal{K}, \quad M_B(\lambda)f = \Gamma_0 S_{\lambda,B}f.$$

• 
$$\widetilde{\mathcal{S}}_{\lambda,B}$$
 and  $\widetilde{M}_B(\lambda)$  defined analogously.

### Relation to resolvent

To be able to study spectral properties of the operator via the M-function, we need to relate the M-function to the resolvent.

### Relation to resolvent

To be able to study spectral properties of the operator via the M-function, we need to relate the M-function to the resolvent.

### Lemma

• 
$$\lambda, \lambda_0 \in \rho(A_B)$$
, then

$$M_B(\lambda) = \Gamma_0(A_B - \lambda_0)(A_B - \lambda)^{-1}S_{\lambda_0,B}$$

## Relation to resolvent

To be able to study spectral properties of the operator via the M-function, we need to relate the M-function to the resolvent.

### Lemma

• 
$$\lambda, \lambda_0 \in 
ho(A_B)$$
, then

$$M_B(\lambda) = \Gamma_0(A_B - \lambda_0)(A_B - \lambda)^{-1}S_{\lambda_0,B}$$

### Theorem (Kreĭn-type formula)

• 
$$C \in \mathcal{L}(\mathcal{K}, \mathcal{H})$$
,  $\lambda \in \rho(A_B) \cap \rho(A_C)$ . Then

$$(A_B - \lambda)^{-1} = (A_C - \lambda)^{-1} - S_{\lambda,C}(I + (B - C)M_B(\lambda))(C - B)\Gamma_0(A_C - \lambda)^{-1}$$

• 
$$B = 0, \lambda \in \rho(A_0) \cap \rho(A_C)$$
, then

$$(A_0 - \lambda)^{-1} = (A_C - \lambda)^{-1} - S_{\lambda,C}(I - CM_0(\lambda))\Gamma_1(A_C - \lambda)^{-1}$$

## Results for poles

#### Theorem

Let  $\mu \in \mathbb{C}$  be an isolated eigenvalue of finite algebraic multiplicity of the operator  $A_B$ . Assume unique continuation holds, i.e.

 $\ker(A_{\max}-\mu)\cap \ker(\Gamma_1)\cap \ker(\Gamma_0) = \ker(\widetilde{A}_{\max}-\bar{\mu})\cap \ker(\widetilde{\Gamma}_1)\cap \ker(\widetilde{\Gamma}_0) = \{0\}.$ 

Then  $\mu$  is a pole of finite multiplicity of  $M_B(\cdot)$  and the order of the pole of  $R(\cdot, A_B)$  at  $\mu$  is the same as the order of the pole of  $M_B(\cdot)$  at  $\mu$ .

# Results for poles

#### Theorem

Let  $\mu \in \mathbb{C}$  be an isolated eigenvalue of finite algebraic multiplicity of the operator  $A_B$ . Assume unique continuation holds, i.e.

 $\ker(A_{\max}-\mu)\cap \ker(\Gamma_1)\cap \ker(\Gamma_0)=\ker(\widetilde{A}_{\max}-\bar{\mu})\cap \ker(\widetilde{\Gamma}_1)\cap \ker(\widetilde{\Gamma}_0)=\{0\}.$ 

Then  $\mu$  is a pole of finite multiplicity of  $M_B(\cdot)$  and the order of the pole of  $R(\cdot, A_B)$  at  $\mu$  is the same as the order of the pole of  $M_B(\cdot)$  at  $\mu$ .

#### Theorem

- Let  $B \in \mathcal{L}(\mathcal{K}, \mathcal{H})$ ,  $\mu \in \mathbb{C}$ .
- Assume there exists  $C \in \mathcal{L}(\mathcal{K}, \mathcal{H})$  such that  $\mu \in \rho(A_C)$ .

Then  $\mu$  is isolated eigenvalue of finite algebraic multiplicity of  $A_B$  iff  $\mu$  is pole of finite multiplicity of  $M_B(\cdot)$ .

In this case, order of the pole of  $R(\cdot, A_B)$  at  $\mu$  is same as order of the pole of  $M_B(\cdot)$  at  $\mu$ .

# A matrix differential operator, (Hain-Lüst operator)

$$A_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix}, \quad \widetilde{A}_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + \overline{q(x)} & \overline{w(x)} \\ \overline{\tilde{w}(x)} & \overline{u(x)} \end{pmatrix},$$

where q, u, w and  $\tilde{w}$  are  $L^{\infty}$ -functions,

# A matrix differential operator, (Hain-Lüst operator)

$$A_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix}, \quad \widetilde{A}_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + \overline{q(x)} & \overline{w(x)} \\ \overline{\tilde{w}(x)} & \overline{u(x)} \end{pmatrix},$$

where q, u, w and  $\tilde{w}$  are  $L^{\infty}$ -functions, and

$$\begin{split} D(A_{\max}) &= D(\widetilde{A}_{\max}) = H^2(0,1) \times L^2(0,1), \\ \Gamma_1 \left( \begin{array}{c} y \\ z \end{array} \right) &= \left( \begin{array}{c} -y'(1) \\ y'(0) \end{array} \right), \quad \Gamma_0 \left( \begin{array}{c} y \\ z \end{array} \right) = \left( \begin{array}{c} y(1) \\ y(0) \end{array} \right), \end{split}$$

# A matrix differential operator, (Hain-Lüst operator)

$$A_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix}, \quad \widetilde{A}_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + \overline{q(x)} & \overline{w(x)} \\ \overline{\tilde{w}(x)} & \overline{u(x)} \end{pmatrix},$$

where q, u, w and  $\tilde{w}$  are  $L^{\infty}$ -functions, and

$$D(A_{\max}) = D(\widetilde{A}_{\max}) = H^{2}(0,1) \times L^{2}(0,1),$$

$$\Gamma_{1}\begin{pmatrix} y\\ z \end{pmatrix} = \begin{pmatrix} -y'(1)\\ y'(0) \end{pmatrix}, \quad \Gamma_{0}\begin{pmatrix} y\\ z \end{pmatrix} = \begin{pmatrix} y(1)\\ y(0) \end{pmatrix},$$

$$A_{B} := A_{\max}|_{\ker(\Gamma_{1} - B\Gamma_{0})},$$

$$\sigma_{ess}(A_{B}) = \operatorname{essran}(u) \quad \text{for any } B \in \mathbb{R}^{2 \times 2}.$$

$$\begin{split} A_{\max} &= \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix} \\ \text{Let} \begin{pmatrix} y \\ z \end{pmatrix} \in \ker(A_{\max} - \lambda). \text{ Then} \\ &-y'' + (q - \lambda)y + \tilde{w}z = 0 \text{ and } wy + (u - \lambda)z = 0, \end{split}$$

$$A_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix}$$
  
Let  $\begin{pmatrix} y \\ z \end{pmatrix} \in \ker(A_{\max} - \lambda)$ . Then  
 $-y'' + (q - \lambda)y + \tilde{w}z = 0$  and  $wy + (u - \lambda)z = 0$ ,  
so

$$z=rac{wy}{\lambda-u} \;\; ext{and} \;\; -y''+(q-\lambda)y+rac{w ilde wy}{\lambda-u}=0.$$

Malcolm Brown (Cardiff)

Image: A mathematical states and a mathem

3 × 1

$$A_{\max} = \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix}$$
  
Let  $\begin{pmatrix} y \\ z \end{pmatrix} \in \ker(A_{\max} - \lambda)$ . Then  
 $-y'' + (q - \lambda)y + \tilde{w}z = 0$  and  $wy + (u - \lambda)z = 0$ ,

SO

$$z = rac{wy}{\lambda - u} \; ext{ and } \; - y'' + (q - \lambda)y + rac{w ilde w y}{\lambda - u} = 0.$$

If w(I) = 0, then u(I) can be changed without affecting y or the *M*-function.

$$\begin{aligned} A_{\max} &= \begin{pmatrix} -\frac{d^2}{dx^2} + q(x) & \tilde{w}(x) \\ w(x) & u(x) \end{pmatrix} \\ \text{Let} \begin{pmatrix} y \\ z \end{pmatrix} \in \ker(A_{\max} - \lambda). \text{ Then} \\ -y'' + (q - \lambda)y + \tilde{w}z = 0 \text{ and } wy + (u - \lambda)z = 0, \end{aligned}$$

SO

$$z = rac{wy}{\lambda - u} \; ext{ and } \; -y'' + (q - \lambda)y + rac{w ilde w y}{\lambda - u} = 0.$$

If w(I) = 0, then u(I) can be changed without affecting y or the *M*-function.

We can not expect the uniqueness of the Borg result to hold in a general setting

# The general setting

What can be shown in the general setting ?

What can be shown in the general setting ? We first introduce the concepts of detectable subspace and of bordered resolvent. What can be shown in the general setting ?

We first introduce the concepts of detectable subspace and of bordered resolvent.

For  $\mu_0 \notin \sigma(A_B)$ , define the space (the bordered resolvent)

$$\mathcal{S} = \operatorname{Span}_{\delta \notin \sigma(A_B)} (A_B - \delta I)^{-1} \operatorname{Ran}(S_{\mu_0,B}),$$

What can be shown in the general setting ?

We first introduce the concepts of detectable subspace and of bordered resolvent.

For  $\mu_0 \notin \sigma(A_B)$ , define the space (the bordered resolvent)

$$\mathcal{S} = \operatorname{Span}_{\delta \notin \sigma(A_B)} (A_B - \delta I)^{-1} \operatorname{Ran}(S_{\mu_0,B}),$$

Our aim is to study the relation between  $M_B(\lambda)$  and the bordered resolvent  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}}$  where for any subspace M,  $P_M$  denotes the orthogonal projection onto M.

What can be shown in the general setting ?

We first introduce the concepts of detectable subspace and of bordered resolvent.

For  $\mu_0 \notin \sigma(A_B)$ , define the space (the bordered resolvent)

$$\mathcal{S} = \operatorname{Span}_{\delta \notin \sigma(A_B)} (A_B - \delta I)^{-1} \operatorname{Ran}(S_{\mu_0,B}),$$

Our aim is to study the relation between  $M_B(\lambda)$  and the bordered resolvent  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}}$  where for any subspace M,  $P_M$  denotes the orthogonal projection onto M.

Our results are of two types, concerning uniqueness and reconstruction. (e.g Borg Levinson compared with Gel'fand-Levitan type results) We first look at gaining information on the M-function from knowledge of the resolvent for a single boundary-condition operator B.

We first look at gaining information on the M-function from knowledge of the resolvent for a single boundary-condition operator B.

Our first theorem concerns uniqueness only.

#### Theorem

Let  $\lambda \in \rho(A_B)$ . Then  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}}$  uniquely determines  $M_B(\lambda)$ . In particular, if also  $\lambda \in \rho(A_C)$ , then  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}} = P_{\overline{S}}(A_C - \lambda)^{-1}|_{\overline{S}}$  implies that  $M_B(\lambda) = M_C(\lambda)$ , and, if additionally  $\lambda \in \rho(A_\infty)$ , then B = C. Here,  $A_\infty = \widetilde{A}^*|_{\ker\Gamma_0}$ .

We first look at gaining information on the M-function from knowledge of the resolvent for a single boundary-condition operator B.

Our first theorem concerns uniqueness only.

#### Theorem

Let  $\lambda \in \rho(A_B)$ . Then  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}}$  uniquely determines  $M_B(\lambda)$ . In particular, if also  $\lambda \in \rho(A_C)$ , then  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}} = P_{\overline{S}}(A_C - \lambda)^{-1}|_{\overline{S}}$  implies that  $M_B(\lambda) = M_C(\lambda)$ , and, if additionally  $\lambda \in \rho(A_\infty)$ , then B = C. Here,  $A_\infty = \widetilde{A}^*|_{\ker \Gamma_0}$ .

In the completely abstract case we need further information to recover  $M_B$ .

イロト イ理ト イヨト イヨト

## Reconstruction from a single boundary-condition operators

### Theorem

Assume we know  $\overline{S}$ ,  $P_{\overline{\tilde{S}}}(A_B - \lambda)^{-1}|_{\overline{S}}$  and the two sets  $\overline{\operatorname{Ran}(S_{\mu,B})}$ ,  $\overline{\operatorname{Ran}(\widetilde{S}_{\widetilde{\mu},B^*})}$  for some  $(\mu,\widetilde{\mu})$  with  $\mu, \overline{\widetilde{\mu}} \in \rho(A_B)$ . Then we can reconstruct  $M_B(\lambda)$  uniquely if B is known.

# Reconstruction from a single boundary-condition operators

#### Theorem

Assume we know  $\overline{S}$ ,  $P_{\overline{\tilde{S}}}(A_B - \lambda)^{-1}|_{\overline{S}}$  and the two sets  $\overline{\operatorname{Ran}(S_{\mu,B})}$ ,  $\overline{\operatorname{Ran}(\widetilde{S}_{\widetilde{\mu},B^*})}$  for some  $(\mu,\widetilde{\mu})$  with  $\mu, \overline{\widetilde{\mu}} \in \rho(A_B)$ . Then we can reconstruct  $M_B(\lambda)$  uniquely if B is known.

A key hypothesis is the assumption that we know the closed ranges of the solution operators.

### Theorem

Assume we know 
$$\overline{\mathcal{S}}$$
,  $P_{\overline{\widetilde{\mathcal{S}}}}(A_B - \lambda)^{-1}|_{\overline{\mathcal{S}}}$  and the two sets  $\overline{\operatorname{Ran}(S_{\mu,B})}$ ,

Ran  $(\widetilde{S}_{\widetilde{\mu},B^*})$  for some  $(\mu,\widetilde{\mu})$  with  $\mu, \overline{\widetilde{\mu}} \in \rho(A_B)$ . Then we can reconstruct  $M_B(\lambda)$  uniquely if B is known.

A key hypothesis is the assumption that we know the closed ranges of the solution operators.

#### Theorem

Assume we know  $\operatorname{Ran} S_{\lambda,B}$  and  $\operatorname{Ran} \widetilde{S}_{\mu,B^*}$  for some  $\lambda, \mu$  for the Hain-Lüst operator. Then the operator is not uniquely determined.

### Theorem

Assume we know 
$$\overline{\mathcal{S}}$$
,  $P_{\overline{\widetilde{\mathcal{S}}}}(A_B - \lambda)^{-1}|_{\overline{\mathcal{S}}}$  and the two sets  $\overline{\operatorname{Ran}(S_{\mu,B})}$ ,

Ran  $(\widetilde{S}_{\widetilde{\mu},B^*})$  for some  $(\mu,\widetilde{\mu})$  with  $\mu, \overline{\widetilde{\mu}} \in \rho(A_B)$ . Then we can reconstruct  $M_B(\lambda)$  uniquely if B is known.

A key hypothesis is the assumption that we know the closed ranges of the solution operators.

#### Theorem

Assume we know  $\operatorname{Ran} S_{\lambda,B}$  and  $\operatorname{Ran} \widetilde{S}_{\mu,B^*}$  for some  $\lambda, \mu$  for the Hain-Lüst operator. Then the operator is not uniquely determined.

However in the case of the Friedrichs model (a first order integrable operator) where the closed range of the solution operator is known, it is determined.

Image: A matrix

By allowing ourselves information from *two* bordered resolvents belonging to different boundary conditions, we obtain reconstruction procedures for the *M*-function.

By allowing ourselves information from *two* bordered resolvents belonging to different boundary conditions, we obtain reconstruction procedures for the *M*-function.

#### Theorem

Assume  $P_{\overline{S}}(A_B - \lambda)^{-1}|_{\overline{S}}$  and  $P_{\overline{S}}(A_C - \lambda)^{-1}|_{\overline{S}}$  are known. In addition, assume that (i)  $\Gamma_0(A_C - \lambda)^{-1}\overline{S}$  and  $\widetilde{\Gamma}_0(A_C - \lambda)^{-*}\overline{\widetilde{S}}$  are known, (ii)  $\Gamma_0(A_C - \lambda)^{-1}\overline{S}$  is dense in  $\mathcal{H}$  and  $\widetilde{\Gamma}_0(A_C - \lambda)^{-*}\overline{\widetilde{S}}$  is dense in  $\mathcal{K}$ , (iii)  $\operatorname{Ran}(B - C)$  is dense in  $\mathcal{H}$  and  $\ker(B - C) = \{0\}$ . Then  $M_B(\lambda)$  can be recovered.