Verified Numerics for ODEs in Isabelle/HOL

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Ordinary Differential Equations

 modeling physics, biology, dynamical systems



- modeling physics, biology, dynamical systems
- no closed form solution



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Problem

correctness of computed enclosures?

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Formalization and Verification

• formalization of \mathbb{R}^n and ODEs in Isabelle

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Result highly trusted code



Applications/Challenges

Oil reservoir: stiff

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- Oil reservoir: stiff
- van-der-Pol: nonlinear

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- Oil reservoir: stiff
- van-der-Pol: nonlinear
- Lorenz attractor: proof of topological properties based on computed enclosures



Formalization and Verification

Optimizations

Lorenz Attractor

Isabelle/HOL: interactive theorem prover

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- higher order logic

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 - functional programming

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 - proofs of properties
 - machine-checked

 $\blacktriangleright \mathbb{N} \rightsquigarrow \mathbb{Z} \rightsquigarrow \mathbb{Q} \rightsquigarrow \mathbb{R}$

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► (Harrison's) multivariate analysis ℝⁿ: e.g.,

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- (Harrison's) multivariate analysis \mathbb{R}^n : e.g.,
 - Taylor series expansions
 - Banach fixed point theorem
- based on axiomatic type classes: e.g.,
 class metric_space =
 fixes dist::"'a ⇒ 'a ⇒ real"
 assumes "dist x y = 0 ↔ x = y"
 assumes "dist x y ≤ dist x z + dist y z"

```
instance real::metric_space
sorry
```

instance complex::metric_space
sorry
$$\dot{\psi}(t) = f(\psi(t)); \psi(t_0) = x_0$$

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 P(ψ) = (t ↦ x₀ + ∫^t_{t₀} f(ψ(τ))dτ)

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no dependent types

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- ▶ flow φ(x₀, t)
 (solution for initial value x₀ at time t)



• Euler step:

 $f \dots$ slope given by ODE $\varphi(x_0, h) = x_0 + h \cdot f(x_0)$

Euler Method • Euler step: $f \dots$ slope given by ODE $\varphi = \begin{bmatrix} \mathcal{O}(h^2) \\ h \cdot f(x_0) \end{bmatrix}$ $\varphi = \begin{bmatrix} \mathcal{O}(h^2) \\ h \cdot f(x_0) \end{bmatrix}$



- Euler step:
 - $f \dots$ slope given by ODE 0
 - $\varphi(x_0,h) = x_0 + h \cdot f(x_0) + O(h^2)$
- set-based Euler step

•
$$x_0 \in X_0$$

enclosed by F, i.e.
$$f(X) \subseteq F(X)$$

 X_0

 $\begin{bmatrix} \mathcal{O}(h^2) \\ h \cdot f(x_0) \end{bmatrix}$

h

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 - $\varphi(X_0, [0; h]) \subseteq Q$



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$$\varphi(X_0, [0; h]) \subseteq Q = certify-stepsize(X_0)$$



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$$\varphi(X_0, [0; h]) \subseteq Q = certify-stepsize(X_0)$$

• Euler_h(X₀) = X₀ + h · F(X₀) + $\frac{1}{2}h^2$ · box (DF(Q)(F(Q)))

Xd

 $O(h^2)$

h

Euler step:



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Theorem $\varphi(X_0,h) \subseteq \operatorname{Euler}_h(X_0)$

 $\begin{bmatrix} \mathcal{O}(h^2) \\ h \cdot f(x_0) \end{bmatrix}$

h



nested evaluations of f



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- higher order approximations



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$$\varphi(x,h) = x + h \cdot (\frac{1}{2}f(x) + \frac{1}{2}f(x+h \cdot f(x)) + O(h^3))$$

Motivation

enclose errors (algorithm/finite precision)

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e.g., intervals / interval arithmetic

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Explicit Round-Off Operation

round every generator collect errors in fresh noise symbols ε_i

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• set \rightsquigarrow list

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- in principle generic!

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Up Next applications/optimizations

- stiff: small step sizes required
- ▶ performance:
 ≈ 20 times slower than
 [Bouissou et al., 2013]
- nontrivial: VNODE fails to maintain precision

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Formalization and Verification

Optimizations

Lorenz Attractor

zonotopes: convex

- zonotopes: convex
- wrapping non-convex sets

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Splitting





 \leadsto







Heuristics

split largest generator of affine form



Heuristics

- split largest generator of affine form
- split when diameter exceeds threshold

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Reduction



Reduction



• $X_C \cap H$ can be smaller

Reduction



- $X_C \cap H$ can be smaller
- geometric zonotope/hyperplane intersection

Van-der-Pol Oscillator



х

Lorenz attractor (reduction)



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Х



Enclosures in Affine Arithmetic

Zonotope

$$\gamma \langle \mathbf{a}_0, \dots, \mathbf{a}_k \rangle = \\ \left\{ \mathbf{a}_0 + \sum_{i=1}^k \varepsilon_i \cdot \mathbf{a}_i \middle| \varepsilon_i \in [-1; 1], \mathbf{a}_i \in \mathbb{R}^n \right\}$$

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$$a_3$$
 a_2
 a_1

Enclosures in Affine Arithmetic

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$\mathsf{Zonotope}\,\cap\,\mathsf{Hyperplane}$

- approximate geometric algorithm [Girard/Le Guernic 2008]
- "proof" not at all formal!
- but similar to convex hull [Knuth: Axioms and Hulls, 1992]

 reduction to two-dimensional problem

Proposition 1. Let G be a hyperplane, $G = \{x \in \mathbb{R}^d : x \cdot n = \gamma\}$, Z a set, and ℓ a vector. Let $\prod_{n,\ell}$ be the following linear transformation:

 $\Pi_{n,\ell} : \mathbb{R}^d \rightarrow \mathbb{R}^2$ $x \mapsto (x \cdot n, x \cdot \ell)$

Then, we have the following equality

 $\{x \cdot \ell : x \in Z \cap G\} = \{y : (\gamma, y) \in \Pi_{n,\ell}(Z)\}$

Proof. Let y belongs to $\{x \cdot \ell : x \in Z \cap G\}$, then there exists x in $Z \cap G$ such that $x \cdot \ell = y$. Since $x \in G$, we have $x \cdot n = \gamma$. Therefore $(\gamma, y) = In_{n,\ell}(x) \in In_{n,\ell}(x)$ because $x \in Z$. Thus, $y \in \{y : (\gamma, y) \in In_{n,\ell}(Z)$. Conversely, $y \in \{y : (\gamma, y) \in In_{n,\ell}(Z)\}$, then $(\gamma, y) \in In_{n,\ell}(Z)$. It follows that there exists $x \in Z$ such that $x \cdot n = \gamma$ and $x \cdot \ell = y$. Since $x \cdot n = \gamma$, it follows that $x \in G$. Thus, $y = x \cdot \ell$ with $x \in Z \cap G$ and it follows that $y \in \{x \cdot \ell : x \in Z \cap G\}$.

 reduction to two-dimensional problem

> lemma inter_proj_eq: fixes n g l defines "G \equiv {x. x • n = g}" shows "($\lambda x. x • l$) ` (Z \cap G) = {y. (g, y) \in ($\lambda x. (x • n, x • l$)) ` Z}" by (auto simp: G_def)

- reduction to two-dimensional problem
- ▶ 2D-zonotope ∩ line

```
lemma inter_proj_eq:
fixes n g l
defines "G \equiv {x. x • n = g}"
shows "(\lambda x. x • l) ` (Z \cap G) =
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- reduction to two-dimensional problem
- 2D-zonotope \cap line
- compute hull of 2D-zonotope: append sorted line segments



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cyclic symmetry:

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tpr

total order in halfplane left of ts

 \implies

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total order in halfplane left of ts sorted[p, q, r]
• translation: $(p+s)(q+s)(r+s) \Leftrightarrow pqr$







q

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addition

$$0pq \implies 0pr \implies 0p(q+r)$$

Close Parenthesis







Formalization and Verification

Optimizations

Lorenz Attractor

Lorenz equations (1963)

$$\dot{x} = 10(y - x)$$
$$\dot{y} = x(28 - z) - y$$
$$\dot{z} = xy - \frac{8}{3}z$$



Edward N. Lorenz

- Lorenz equations (1963)
- numerical simulations



Lorenz attractor

- Lorenz equations (1963)
- numerical simulations
- conjecture: chaos (strange attractor)



Smale's 14th problem

- Lorenz equations (1963)
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- conjecture: chaos (strange attractor)
- proof: Tucker (1999), relying on C++-program



Warwick Tucker

- Lorenz equations (1963)
- numerical simulations
- conjecture: chaos (strange attractor)
- proof: Tucker (1999), relying on C++-program
- correctness of program?



1. attracting set (numerically enclose ODE)

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- 2. sensitive dependence on initial conditions (numerically enclose variational equation)

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Contribution

part 1. using *verified* ODE solver

3D continuous dynamics



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- standard reduction: return plane Σ iteration of 2D return map $R: \Sigma \to \Sigma$



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 - $\varphi(x, t)$... solution with initial value x after time t



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Result verified a sufficiently precise N

Bound on N



► blue: N_{Tucker}, black: N_{Isabelle}

Lorenz Attractor (Front)



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Lorenz Attractor (Left)



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Lorenz Attractor (Bottom)



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verification is feasible and useful:

verified computation as part of proof

Conclusion

verification is feasible and useful:

- verified computation as part of proof
- novel combination of affine arithmetic/Runge-Kutta methods/reduction

Verified Numerics for ODEs in Isabelle/HOL

Fabian Immler

MAP 2016



