#### Fast computation of exp(Toeplitz)

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Aim

#### Given an $n \times n$ Toeplitz matrix

$$\mathcal{T} = \begin{bmatrix} t_0 & t_{-1} & \cdots & t_{-n+1} \\ t_1 & t_0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & t_{-1} \\ t_{n-1} & \cdots & t_1 & t_0 \end{bmatrix},$$

compute exp(T) in less than  $O(n^3)$  operations.

#### **Motivation**

- Discretization of partial integro-differential equations (PIDEs) with a shift-invariant kernel.
- Pricing of single-asset options modelled by jump-diffusion processes.

Example: Merton model requires solution of PIDE

$$\omega_t = \frac{\nu^2}{2}\omega_{\xi\xi} + \left(\mathbf{r} - \lambda\kappa - \frac{\nu^2}{2}\right)\omega_{\xi} - (\mathbf{r} + \lambda)\omega + \lambda \int_{-\infty}^{\infty} \omega(\xi + \eta, t)\phi(\eta)d\eta$$

on domain  $(\xi, t) \in (-\infty, \infty) \times [0, t_e]$ .

Truncation of  $(-\infty,\infty)$  and discretization by standard finite differences/rectangle rule  $\rightsquigarrow$ 

 $w(t+h) = \exp(hT)w_t.$ 

Explicit availability of exp(hT) useful for computing (many) prices at fixed time intervals (e.g., for every day).

#### Selected related work

If T is (block-)triangular (block-)Toeplitz then exp(T) inherits this structure:

D. A. Bini, S. Dendievel, G. Latouche, and B. Meini, Computing the exponential of large block-triangular block-Toeplitz matrices encountered in fluid queues, arXiv:1502.07533, 2015.

Fast Toeplitz solvers combined with rational Arnoldi for computing exp(T)b:

S. T. Lee, H.-K. Pang, and H.-W. Sun, Shift-invert Arnoldi approximation to the Toeplitz matrix exponential, SIAM J. Sci. Comput., 32 (2010), pp. 774–792,

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#### Outline

- 1. Displacement rank
- 2. Approximate displacement rank
- 3. Scaling and squaring
- 4. Scaling and squaring for Toeplitz matrices

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5. Numerical experiments

## **Displacement rank**

#### Displacement rank

Consider displacement

$$abla(A) = A - ZAZ^*, \qquad Z = \begin{bmatrix} 0 & & & \\ 1 & 0 & & \\ & \ddots & \ddots & \\ & & 1 & 0 \end{bmatrix}$$

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For A = Toeplitz:

$$\nabla(T) = T - ZTZ^* = \begin{bmatrix} t_0 & t_{-1} & \cdots & t_{-n+1} \\ t_1 & 0 & \ddots & 0 \\ \vdots & 0 & \ddots & \vdots \\ t_{n-1} & 0 & \cdots & 0 \end{bmatrix},$$

Toeplitz matrix T has rank( $\nabla(T)$ ) at most 2.

#### Reconstruction from displacement

 $A - ZAZ^* = GB^*$ 

with  $B, G \in \mathbb{C}^{n \times r}$  is matrix Stein equation with unique solution

$$\begin{array}{lll} A = \mathcal{T}(G,B) &:= & \sum_{k=0}^{n-1} Z^k G B^* (Z^*)^k \\ &= & L(g_1) U(b_1^*) + L(g_2) U(b_2^*) + \dots + L(g_r) U(b_r^*), \end{array}$$

where

$$L(x) := \begin{bmatrix} x_1 & 0 & \cdots & 0 \\ x_2 & x_1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ x_n & \cdots & x_2 & x_1 \end{bmatrix}, \qquad U(x) := \begin{bmatrix} x_1 & x_2 & \cdots & x_n \\ 0 & x_1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & x_2 \\ 0 & \cdots & 0 & x_1 \end{bmatrix}$$

 $\rightarrow$  Exact and fast reconstruction of matrix from its generator (*G*, *B*).

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## $T^{-1}$ has displacement rank $\leq 2$

Well-known results:

- Inverse of Toeplitz matrix T has displacement rank  $\leq$  2.
- General matrix A: rank $(\nabla(A^{-1})) \leq \operatorname{rank}(\nabla(A))+2$

Proof based on embedding into larger matrix of low displacement rank and utilizing that Schur complements preserve displacement ranks.

Selected references:

- T. Kailath and A. Sayed, Displacement structure: theory and applications, SIAM Review, 37 (1995), pp. 297–386.
- T. Kailath and A. H. Sayed, Fast Reliable Algorithms for Matrices with Structure, SIAM, Philadelphia, 1999.
- V. Olshevsky, ed., Structured matrices in mathematics, computer science, and engineering. I, vol. 280 of Contemporary Mathematics, American Mathematical Society, Providence, RI, 2001.

#### expm(T) does not have low displacement rank

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#### expm(T) does not have low displacement rank

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#### expm(T) often has low *approximate* displacement rank



# Approximate displacement rank

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### Stability of generator

Lemma. [Pan'1993, DK/Luce'2016] Displacement  $\nabla(A)$  for  $A \in \mathbb{C}^{n \times n}$  satisfies

$$\frac{1}{2} \|\nabla(A)\|_* \le \|A\|_* \le n \|\nabla(A)\|_*,$$

for any unitarily invariant norm  $\|\cdot\|_*$ .

Consequences:

- ▶ By linearity of  $\nabla$ :  $\frac{1}{2} \|\nabla(A) - \nabla(\tilde{A})\|_* \le \|A - \tilde{A}\|_* \le n \|\nabla(A) - \nabla(\tilde{A})\|_*.$
- ► Low-rank truncation of generator ⇔ approximation of matrix.

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#### A priori result by rational approximation

Theorem. [DK/Luce'2016] Let *T* Toeplitz, *p*, *q* polynomials. Then  $r(T) = p(T)[q(T)]^{-1}$  has displacement rank at most

 $2 \max\{\deg p, \deg q\} + 1.$ 

Theorem. [Gonchar/Rakhmanov'1987]  $\exists$  constant C such that

 $\inf_{p_1,p_2\in \mathcal{P}_s}\max_{\lambda\in(-\infty,0]}|e^{\lambda}-p_1(\lambda)/p_2(\lambda)|\leq C\,V^{-s}$ 

holds for all  $s \ge 1$  with  $V \approx 9.28903...$ 

Corollary. Let T be symmetric negative definite. Then

 $\min\{\|\exp(T) - A\|_2 : \operatorname{rank}(\nabla(A)) \le 2s + 1\} \le C V^{-s}.$ 

 Technique extends to other rational approximation results (e.g., [López-Fernández/Palencia/Schädle'2006] for sectoral operators).

# Scaling & Squaring

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#### Scaling & Squaring

Basic idea:

- 1. Scale  $\tilde{A} = 2^{-\rho}A$ ,  $\rho \ge 0$ , s.t.  $\|\tilde{A}\| \lesssim 1$ .
- 2. Compute (low-degree) rational approximation  $\tilde{E} = p(\tilde{A})q(\tilde{A})^{-1} \approx \exp(\tilde{A}).$
- 3. Compute  $E = \tilde{E}^{2^{\rho}}$  by squaring  $\rho$  times.

Remarks:

- No properties on A known: choose diagonal Padé approximation p/q.
   Basis of MATLAB's expm, [Higham'2008], [Higham'2009], ...
- Eigenvalues of A on or very close to negative real axis: choose subdiagonal Padé approximation p/q.
   Basis of sexpm by [Güttel/Nakatsukasa'2016].

### Scaling & Squaring

Input: General matrix  $A \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(A)$ .

- 1: Compute  $||A||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$

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- 3: Scale  $A \leftarrow 2^{-\rho}A$ .
- 4: Compute  $U \leftarrow p_m(A)$ ,  $V \leftarrow q_m(A)$ .
- 5: Compute  $E \leftarrow UV^{-1}$ .
- 6: for k = 1 to  $\rho$  do
- 7:  $E \leftarrow E \cdot E$ .
- 8: end for

Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(T)$ .

- 1: Compute  $||T||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$

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- 3: Scale  $T \leftarrow 2^{-\rho} T$ .
- 4: Compute  $U \leftarrow p_m(T)$ ,  $V \leftarrow q_m(T)$ .
- 5: Compute  $E \leftarrow UV^{-1}$ .
- 6: for k = 1 to  $\rho$  do
- 7:  $E \leftarrow E \cdot E$ .
- 8: end for

Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(T)$ .

- 1: Compute  $||T||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$

 $\{\mathcal{O}(n)\}\$ 

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- 3: Scale  $T \leftarrow 2^{-\rho} T$ .
- 4: Compute  $U \leftarrow p_m(T)$ ,  $V \leftarrow q_m(T)$ .
- 5: Compute  $E \leftarrow UV^{-1}$ .
- 6: for k = 1 to  $\rho$  do
- 7:  $E \leftarrow E \cdot E$ .
- 8: end for

Remark:

Simple to see that  $||T||_1$  can be computed in  $\mathcal{O}(n)$  operations.

Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(T)$ .

- 1: Compute  $||T||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$

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- 3: Scale  $T \leftarrow 2^{-\rho} T$ .
- 4: Compute  $U \leftarrow p_m(T)$ ,  $V \leftarrow q_m(T)$ .
- 5: Compute  $E \leftarrow UV^{-1}$ .
- 6: for k = 1 to  $\rho$  do
- 7:  $E \leftarrow E \cdot E$ .
- 8: end for

Remark:

► Rescale only first column and row of *T*.

Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(T)$ .

- 1: Compute  $||T||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{a_m(z)}$
- 3: Scale  $T \leftarrow 2^{-\rho} T$ .
- 4:  $(G_{\rho}, B_{\rho}) \leftarrow$  generator for  $p_m(T)$
- 5:  $(G_q, B_q) \leftarrow \text{generator for } q_m(T)$
- 6: Compute  $E \leftarrow UV^{-1}$ .
- 7: for k = 1 to  $\rho$  do
- 8:  $E \leftarrow E \cdot E$ .
- 9: end for

Remark:

 Special case of construction for rational functions of Toeplitz matrices.

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Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Accurate approximation  $E \approx \exp(T)$ .

- 1: Compute  $||T||_1$
- 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$

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- 3: Scale  $T \leftarrow 2^{-\rho} T$ .
- 4:  $(G_p, B_p) \leftarrow \text{generator for } p_m(T)$
- 5:  $(G_q, B_q) \leftarrow \text{generator for } q_m(T)$
- 6:  $(G, B) \leftarrow$  generator for  $r_m(T) = q_m(T)^{-1} p_m(T)$
- 7: for k = 1 to  $\rho$  do
- 8:  $E \leftarrow E \cdot E$ .
- 9: end for

Remark:

- Computation of (G, B) from G<sub>p</sub>, B<sub>p</sub>, G<sub>q</sub>, B<sub>q</sub> requires solution of O(m) Toeplitz-like systems of size n × n.
- ► Fast algorithms (GKO)  $\rightsquigarrow$  complexity  $\mathcal{O}(m^2n^2)$ .
- Superfast alg. [Xia/Xi/Gu'2012]  $\rightarrow$  complexity  $\mathcal{O}(m^2 n \log n)$ .

Input: Toeplitz matrix  $T \in \mathbb{C}^{n \times n}$ .

Output: Generator (G, B) for accurate approx.  $E \approx \exp(T)$ .

1: Compute  $||T||_1$  $\{\mathcal{O}(n)\}\$ 2: Choose scaling parameter  $\rho$  and Padé approximant  $r_m(z) = \frac{p_m(z)}{q_m(z)}$ 3: Scale  $T \leftarrow 2^{-\rho}T$ .  $\{\mathcal{O}(n)\}$ 4:  $(G_p, B_p) \leftarrow$  generator for  $p_m(T)$  $\{\mathcal{O}(mn \log n)\}$ 5:  $(G_a, B_a) \leftarrow$  generator for  $q_m(T)$  $\{\mathcal{O}(mn \log n)\}$ 6:  $(G, B) \leftarrow$  generator for  $r_m(T) = q_m(T)^{-1} \rho_m(T)$  $\{\mathcal{O}(m^2n^2)\}$ 7: for k = 1 to  $\rho$  do 8:  $(\tilde{G}, \tilde{B}) \leftarrow$  generator for  $\mathcal{T}(G, B)^2$  $\{\mathcal{O}(m^2 n \log n)\}$  $(G, B) \leftarrow \text{compress} (\tilde{G}, \tilde{B})$  $\{\mathcal{O}(m^2n)\}$ 9: 10: end for

Remark:

Recompression = low-rank truncation of generator needed to avoid excessive rank growth for large ρ

## Numerical experiments

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#### Accuracy

- Toeplitz matrices from the structured matrix toolbox [Redivo-Zaglia/Rodriguez'2012].
- Implementation of GKO from drsolve package [Aricò/Rodriguez'2010].



Relative error  $\|\exp(T) - \exp(T)\|_2/\|\exp(T)\|_2$ .

#### Numerical displacement ranks

- Toeplitz matrices from the structured matrix toolbox [Redivo-Zaglia/Rodriguez'2012].
- Implementation of GKO from drsolve package [Aricò/Rodriguez'2010].



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Numerical displacement ranks of expm(T) and expmt(T).

#### Execution time for Merton model

Parameters of Merton model chosen as in [Lee/Pang/Sun'2010].



#### Accuracy for Merton model

Parameters of Merton model chosen as in [Lee/Pang/Sun'2010].



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#### Numerical displacement rank for Merton model

Parameters of Merton model chosen as in [Lee/Pang/Sun'2010].



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#### Numerical displacement rank for Merton model

Parameters of Merton model chosen as in [Lee/Pang/Sun'2010].



Evolution of displacement ranks during squaring phase for n = 4096.

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#### Conclusions

- O(n<sup>2</sup>) algorithm for exp(Toeplitz) based on approximate displacement rank and careful adaptation of scaling & squaring.
- Could be reduced to  $\mathcal{O}(n \log n)$ .
- Various extensions possible (other matrix functions, other structures).

#### More details in

DK and Robert Luce. Fast computation of the matrix exponential for a Toeplitz matrix, 2016. Available from http://anchp.epfl.ch.

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