MPDE16, Aix-Marseille University 6th September 2016

Anticipating critical transitions of chaotic attractors through boundary crises

Matthew Adamson

Institute of Environmental Systems Research Universität Osnabrück

Motivation: Erratic population collapses

- Lots of work on early warning signals for critical transitions, but this mostly focuses on local bifurcations.
- There are also many critical transitions in nature featuring erratic population collapses.
- The most likely explanation for these collapses is the collision of a growing chaotic attractor with the boundary of another attractor.

Boundary crises of chaotic attractors

- Often, chaotic attractors aren't globally attracting and the system is bistable.
- Basins of attraction are separated by some boundary manifold.



Boundary crises of chaotic attractors

- Often, chaotic attractors aren't globally attracting and the system is bistable.
- Basins of attraction are separated by some boundary manifold.



Boundary crises of chaotic attractors

- Often, chaotic attractors aren't globally attracting and the system is bistable.
- Basins of attraction are separated by some boundary manifold.
- As parameters change, the chaotic attractor can collide with this boundary and disappear.



Anticipating boundary crises?

Anticipating boundary crises is challenging compared to other critical transitions:

- They're nonlocal and inherently nonlinear.
- Analysis tends to be system-specific. So it's difficult to obtain generic methods of prediction.
- So is it worth trying?



Collapses in Fisheries from 1955-2005



Mullon, Fréon and Cury (2005), Fish and Fisheries

Figure 2 Typical observed patterns of catch time series: (a) no collapse: Atlantic herring in Sweden, (b) plateaushaped collapse: Atlantic cod in Canada, (c) erratic collapse: Atlantic cod in Greenland, (d) smooth collapse: European hake in the UK.

Collapses in Fisheries from 1955-2005



Mullon, Fréon and Cury (2005), Fish and Fisheries

Figure 2 Typical observed patterns of catch time series: (a) no collapse: Atlantic herring in Sweden, (b) plateaushaped collapse: Atlantic cod in Canada, (c) erratic collapse: Atlantic cod in Greenland, (d) smooth collapse: European hake in the UK.

- The simplest case of a boundary crisis is that of the discrete map shown here.
- If the map changes so that att_{min} is below thres the threshold we have a boundary crisis.



- The simplest case of a boundary crisis is that of the discrete map shown here.
- If the map changes so that att_{min} is below threshold the threshold we have a boundary crisis.



- The simplest case of a boundary crisis is that of the discrete map shown here.
- If the map changes so that att_{min} is below threshold the threshold we have a att_{min} boundary crisis.



- The simplest case of a boundary crisis is that of the discrete map shown here.
- If the map changes so that att_{min} is below threshold the threshold we have a att_{min} boundary crisis.
- So far so good, but in a generic method for anticipating boundary crises, we can't rely on particular functional forms...



Partially specified humped discrete time models

So we want to consider 1D maps $x_{t+1} = f(x_t)$ where:

- l(x) < f(x) < u(x) for some bounds l and u,
- f'(x) > 0, $x < x_{\max}$
- f'(x) < 0, $x > x_{\max}$



Bounds of the critical threshold

It's easy to find the minimum and maximum boundary for any function passing between u(x) and l(x). They are the lowest intersections of the identity line and u and l, respectively.



Bounds of the lowest possible attractor value

It's not much harder to find the minimum and maximum lower bound on an attractor.

This just involves `reflecting' points in the identity line and considering the extreme cases.



Plots of the probability of persistence

- The max and min values of the boundary value and the attractor lower bound form a rectangle.
- We have regions of possible extinction or necessary persistence.
- The relative areas serve as an estimate of the extinction possibility.



Allowing negative numbers prevents information loss

Probability of a system changing in time

- We can construct upper and lower bounds, u and l that change in time.
- Then see how the probability of persistence changes with time.
- When it drops to 50% we should expect extinction.



Demonstration: Tritrophic Rosenzweig-MacArthur model

To test the method, we've applied it to the following tritrophic food chain model, with a slow increase in the carrying capacity, K.

For information on this system and the boundary crisis involved see e.g.:

- Hastings, A., Powell, T., 1991. Chaos in a Three-Species Food Chain. Ecology
- McCann, K., Yodzis, P., 1994. Nonlinear Dynamics and Population Disappearances. The American Naturalist

$$\frac{dx_1}{dt} = rx_1 \left(1 - \frac{x_1}{K} \right) - \frac{a_2 x_1}{b_2 + x_1} x_2 \tag{1}$$

$$\frac{dx_2}{dt} = c_2 \frac{a_2 x_1}{b_2 + x_1} x_2 - d_2 x_2 - \frac{a_3 x_2}{b_3 + x_2} x_3 \tag{2}$$

$$\frac{dx_3}{dt} = c_3 \frac{a_3 x_2}{b_3 + x_2} x_3 - d_3 x_3 \tag{3}$$

x₁: Prey
x₂: Predator
x₃: Top Predator

Demonstration: Deterministic time series

The resulting time series is shown here with the bifurcation diagram at the corresponding time.

Note two challenges:

- The periodic windows throughout much of the time series.
- The transient dynamics after the boundary crisis.



McCann & Yodzis, 1994, Am. Nat.

Successful prediction



Less successful prediction



window

Predictive success vs calibration window



Effects of 0.5% noise





Conclusion: Noise generally seems to stop the method from missing the extinction completely.

Effects of 1% noise





Conclusion: Noise generally seems to stop the method from missing the extinction completely.

Conclusions

- Method aims to predict boundary crises of chaotic attractors by representing chaotic time-series by uncertain, evolving, humpshaped maps.
- We've proved the concept works by predicting a collapse in a continuous time model.
- The method struggles with periodic windows, but noise seems to help (for once!)