

Regularity of the optimal sets for spectral functionals: Part II, some generalizations

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Works with Susanna Terracini and Bozhidar Velichkov

- 1 Introduction (brief recall of the sum case)
- 2 Extension to more general functionals

The sum functional

We are dealing with the shape optimization problem:

$$\min \left\{ \lambda_1(\Omega) + \cdots + \lambda_k(\Omega) : \Omega \subset \mathbb{R}^d, \textit{open}, |\Omega| = 1 \right\},$$

which is equivalent with a scaling argument to

$$\min \left\{ \lambda_1(\Omega) + \cdots + \lambda_k(\Omega) + \Lambda |\Omega| : \Omega \subset \mathbb{R}^d, \textit{open} \right\},$$

for some Lagrange multiplier $\Lambda > 0$.

The free boundary formulation

For a vector $V = (v_1, \dots, v_k) \in H^1(\mathbb{R}^d, \mathbb{R}^k)$, we consider the energy functional:

$$\begin{aligned}\mathcal{F}_0(V) &:= \int_{\mathbb{R}^d} |\nabla V|^2 dx + \Lambda |\{|V| > 0\}| \\ &= \sum_{i=1}^k \int_{\mathbb{R}^d} |\nabla v_i|^2 dx + \Lambda |\{v_1^2 + \dots + v_k^2 > 0\}|.\end{aligned}$$

The vector of normalized eigenfunctions $U = (u_1, \dots, u_k)$ for the shape optimization problem for the sum of eigenvalues solves:

$$\min \left\{ \mathcal{F}_0(V) : V \in H^1(\mathbb{R}^d, \mathbb{R}^k), \int_{\mathbb{R}^d} v_i v_j dx = \delta_{ij} \right\}.$$

Regularity of optimal shapes: the sum functional

Theorem (M., Terracini, Velichkov)

Let Ω^* be an optimal set for the problem:

$$\min \left\{ \lambda_1(\Omega) + \cdots + \lambda_k(\Omega) : \Omega \subset \mathbb{R}^d, \text{ open}, |\Omega| = 1 \right\},$$

then Ω^* is connected and its topological boundary is the disjoint union of a regular part $\text{Reg}(\partial\Omega^*)$ and of a singular set $\text{Sing}(\partial\Omega^*)$. $\text{Reg}(\partial\Omega^*)$ is relatively open and C^∞ regular, while $\text{Sing}(\partial\Omega^*)$ is relatively closed and such that

- If $d < d^*$, then $\text{Sing}(\partial\Omega^*) = \emptyset$,
- If $d = d^*$, then $\text{Sing}(\partial\Omega^*)$ is made by a finite number of isolated points,
- If $d > d^*$, then $\dim_H(\text{Sing}(\partial\Omega^*)) \leq d - d^*$.

Key steps in the proof

- Pass to a free-boundary problem
- Nondegeneracy
- Monotonicity formula
- Blow-up analysis
- Optimality condition in a viscosity sense
- Boundary Harnack and reduction to the one-phase case

We wish to extend our results to the more general case:

$$\min \left\{ F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) : \Omega \subset \mathbb{R}^d, \text{quasi-open}, |\Omega| = 1 \right\},$$

for functionals $F: \mathbb{R}^k \rightarrow \mathbb{R}$ increasing in each variable and lower semicontinuous.

The case that we have in mind (and we are currently not able to treat) is

$$\min \left\{ \lambda_k(\Omega) : \Omega \subset \mathbb{R}^d, \text{quasi-open}, |\Omega| = 1 \right\},$$

What are the main problems?

- Free boundary equivalent?
- Lagrange multiplier?
- Optimality condition (even formally)?
- And when λ_1 is missing?

Symmetric and regular functions

Definition

We say that $\varphi \in \mathcal{G}$ if $\varphi: \mathcal{S}_k(\mathbb{R}) \rightarrow \mathbb{R}$ is C^1 in $\mathcal{S}_k(\mathbb{R}) \setminus \{0\}$ and

$$\varphi(M) = \varphi(P^T M P), \quad \text{for all } M \in \mathcal{S}_k(\mathbb{R}), P \in \mathcal{O}_k(\mathbb{R}).$$

Moreover we consider the restriction ψ of φ to the space of the diagonal matrices, that is, $\psi(a_1, \dots, a_k) = \varphi(\text{diag}(a_1, \dots, a_k))$ and we require the following conditions:

- $\frac{\partial \psi}{\partial a_i} > 0$ on $(\mathbb{R}^+)^k$ for all $i = 1, \dots, k$,
- For each i and $\bar{a}_1, \dots, \bar{a}_{i-1}, \bar{a}_{i+1}, \dots, \bar{a}_k > 0$, we have

$$\psi(\bar{a}_1, \dots, \bar{a}_{i-1}, a_i, \bar{a}_{i+1}, \dots, \bar{a}_k) \rightarrow \infty, \quad \text{as } a_i \rightarrow \infty.$$

Examples of $\varphi \in \mathcal{G}$:

- $\varphi(M) = (\text{trace}(M^p))^{1/p}$, then $\psi(a_1, \dots, a_k) = \left(\sum_{i=1}^k a_i^p\right)^{1/p}$
- $\varphi(M) = \det(M)$, then $\psi(a_1, \dots, a_k) = \prod_{i=1}^k a_i$

Corresponding eigenvalues functionals:

$$\left(\sum_{i=1}^k \lambda_i(\cdot)^p\right)^{1/p}, \quad \prod_{i=1}^k \lambda_i(\cdot)$$

Why the class \mathcal{G} is nice?

Given $U \in H_0^1(\Omega, \mathbb{R}^k)$, we define the $k \times k$ symmetric matrix

$$M(U) = \left(\int_{\Omega} \nabla u_i \cdot \nabla u_j \, dx \right)_{i,j=1,\dots,k}$$

Our goal is to study the problem

$$\min \left\{ \varphi(M(U)) : U \in H_0^1(\Omega, \mathbb{R}^k), \int_{\Omega} u_i u_j \, dx = \delta_{ij} \right\}$$

Remark (Ramos, Tavares, Terracini): If $\varphi \in \mathcal{G}$, then the minimum is achieved for a U such that $M(U)$ is a *diagonal matrix*.

In other words, for $\varphi \in \mathcal{G}$:

$$\begin{aligned} & \min \left\{ \varphi(M(U)) : U \in H_0^1(\Omega, \mathbb{R}^k), \int_{\Omega} u_i u_j \, dx = \delta_{ij} \right\} \\ &= \min \left\{ \varphi(M(U)) : U \in H_0^1(\Omega, \mathbb{R}^k), \int_{\Omega} u_i u_j \, dx = \delta_{ij} \right. \\ & \quad \left. \text{and } \int_{\Omega} \nabla u_i \cdot \nabla u_j \, dx = 0, \text{ for } i \neq j \right\} \end{aligned}$$

Remark (Ramos, Tavares, Terracini): If $\varphi(M) = \varphi(P^T M P)$ for all $M \in \mathcal{S}_k(\mathbb{R})$ and $P \in \mathcal{O}_k(\mathbb{R})$, then

$$\frac{\partial \varphi}{\partial \xi_{ij}}(D) = 0,$$

for all diagonal matrix D when $i < j$.

PDE solved by U

For each $U \in H_0^1(\Omega, \mathbb{R}^k)$ optimal for the minimum problem above with $\varphi \in \mathcal{G}$, we have

$$-a_i \Delta u_i = \sum_{j=1}^k \mu_{ij} u_j, \quad \forall i = 1, \dots, k,$$

where

$$a_i := \frac{\partial \varphi}{\partial \xi_{ii}}(M(U)) > 0,$$

and, since $M(U)$ is a diagonal matrix, also $(\mu_{ij})_{i,j}$ is diagonal, more precisely

$$\mu_{ij} = \mu_{ji} := \delta_{ij} a_i \int_{\Omega} |\nabla u_i|^2 = \delta_{ij} a_i \lambda_i(\Omega).$$

In the end, the equation that we get is

$$-a_i \Delta u_i = \mu_{ii} u_i, \quad \forall i = 1, \dots, k.$$

Optimality condition and monotonicity functional

The monotonicity functional becomes:

$$\begin{aligned} \phi(x_0, r) := & \frac{1}{r^d} \left(\int_{B_r(x_0)} \left(\sum_{i=1}^k a_i |\nabla u_i|^2 \right) dx + \Lambda |\{|U|^2 > 0\} \cap B_r(x_0)| \right) \\ & - \frac{1}{r^{d+1}} \int_{\partial B_r(x_0)} \sum_{i=1}^k a_i u_i^2 d\mathcal{H}^{d-1} \end{aligned}$$

Optimality condition and monotonicity functional

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The optimality condition reads as:

$$\sum_{i=1}^k a_i |\nabla u_i|^2 = \Lambda, \quad \text{on } \partial\{|U| > 0\}.$$

A small class of functionals?

Problem: not all smooth functions of eigenvalues are smooth (C^1) symmetric functions.

Good examples are:

$$\lambda_1 + \cdots + \lambda_k, \quad (\lambda_1^p + \cdots + \lambda_k^p)^{1/p}, \quad \prod_{i=1}^k \lambda_i.$$

But...

$$\lambda_k = \max_{i=1, \dots, k} \lambda_i = \lim_{p \rightarrow \infty} (\lambda_1^p + \cdots + \lambda_k^p)^{1/p},$$

is only Lipschitz continuous.

So an approximation argument is needed when dealing with the regularity for the functional λ_k !

An intermediate step

An easier problem than λ_k could be the study of functionals:

$$F: \mathbb{R}^k \rightarrow \mathbb{R},$$

(locally) Lipschitz continuous, non-decreasing in each variable and **strictly increasing** in the first variable.

Examples: $\lambda_1 + \lambda_k$, $\lambda_1^2 + \lambda_k$.

Problems also in this case?

- We need also an approximation in the measure: no clear Lagrange multiplier!
- Approximation of the functional from the class \mathcal{G} .
- Lipschitz continuity not of all eigenfunctions.

Thanks!