# Wulff shape characterizations in overdetermined anisotropic elliptic problems

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## **Capacity problem**

 $\begin{cases} \Delta u = 0 & \text{in } \mathbb{R}^N \setminus \overline{\Omega}, \\ u = 1 & \text{on } \partial \Omega, \\ u \to 0 & \text{if } |x| \to \infty. \end{cases}$ 

 $\rightsquigarrow$   $Cap(\Omega) = \min_{v \in \mathcal{A}} \int_{\mathbb{R}^N} \frac{1}{2} |Dv|^2,$ 

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where  $\mathcal{A} = \{ v \in C_0^{\infty}(\mathbb{R}^N), v \ge 1 \text{ in } \Omega \}.$ 

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what happens in an anisotropic dielectic or for potential-type conduction laws?

We can expect an anisotropic norm to play a crucial role!

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#### Newtonian p-Capacity:

$$Cap_{\rho}(\Omega) = \min_{\boldsymbol{v}\in\mathcal{A}}\int_{\mathbb{R}^{N}} \frac{1}{\rho} |\boldsymbol{D}\boldsymbol{v}|^{\rho},$$

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Let  $H : \mathbb{R}^N \to \mathbb{R}$  be a regular norm in  $\mathbb{R}^N_*$ :

(i) *H* is convex;

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#### NOTICE: $B_{H_0}$ is still uniformly convex.

Let  $H : \mathbb{R}^N \to \mathbb{R}$  be a regular norm in  $\mathbb{R}^N_*$  its dual norm is  $H_0(x) = \sup_{\xi \neq 0} \frac{x \cdot \xi}{H(\xi)}$ , for  $x \in \mathbb{R}^N$ .

Notice:  $x \in \Omega \subseteq \mathbb{R}^N \iff H_0$  norm of  $\mathbb{R}^N$ .  $Du(x) \in$ dual space of  $\mathbb{R}^N \iff H$  norm of  $\mathbb{R}^N$  (dual space).

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Let  $H : \mathbb{R}^N \to \mathbb{R}$  be a regular norm in  $\mathbb{R}^N_*$  its **dual norm** is  $H_0(x) = \sup_{\xi \neq 0} \frac{x \cdot \xi}{H(\xi)}$ , for  $x \in \mathbb{R}^N$ .

Notice:  $x \in \Omega \subseteq \mathbb{R}^N \quad \Leftrightarrow H_0 \text{ norm of } \mathbb{R}^N.$  $Du(x) \in \text{dual space of } \mathbb{R}^N \quad \Leftrightarrow H \text{ norm of } \mathbb{R}^N \text{ (dual space).}$ 

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### **Def.** $\Omega$ is Wulff shape of *H* if $\Omega = rB_{H_0}$ for some r > 0.

that is  $\Omega$  is an anisotropic ball for the dual norm  $H_0$ .

**Main results:** looking at the anisotropic capacity problem  $\rightsquigarrow$  find conditions on the electrostatic potential *u* which guarantee the Wulff shape of the domain  $\Omega$ 

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### **References on anisotropic results**

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   maximum principles, Wulff shape;
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**Newton's inequality:** If W = BC, with  $B, C \in \mathbb{R}^{N \times N}$  symmetric, *B* positive definite, then

$$S_2(W) \leq \frac{N-1}{2N} tr(W)^2.$$

Moreover, if  $tr(W) \neq 0$  and equality holds, then  $W = \gamma I$ ,. [A. Cianchi, P. Salani, Math. Ann. 2009] where  $S_2(A)$  is the elementary symmetric function of A of order 2.

**Anisotropic Aleksandrov Theorem:** If  $M_H(\Omega)$  is constant then  $\Omega$  is Wulff shape.

[He, Li, Ma, Ge, Indiana Univ, 2009] where  $M_H(x) = H_{ij}v_i^j$  is the anisotropic mean curvature.

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**Theorem.** Let *H* be a regular strictly convex norm of  $\mathbb{R}^{N}_{*}$ ; assume  $\Omega$  to be convex and let *u* be a solution to:

$$(Pb): \begin{cases} \Delta_p^H u = 0 & \text{in } \mathbb{R}^N \setminus \overline{\Omega} \\ u = 1 & \text{on } \partial\Omega, \\ u \to 0 & \text{if } |x| \to \infty, \end{cases}$$

for p < N. The following are equivalent: H(Du) = C on  $\partial\Omega$ ,  $\Leftrightarrow$  equality holds in Newton's inequality for  $\nabla^2_H v$  $\Leftrightarrow \Omega$  is Wulff shape of H.

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 [Brandolini, Nitsch, Salani, Trombetti, 08] for classical interior Serrin pb;
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**AIM**: H(Du) = C on  $\partial \Omega$ ,  $\Rightarrow$  equality holds in Newton  $\Rightarrow \Omega$  Wulff shape.

• auxiliary pb for 
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►  $W = \nabla^2 V_p D^2 v$ , anisotropic Hessian where  $V_p(\xi) = \frac{1}{p} H^p(\xi)$ so that  $\Delta_H v = tr(W)$ ;

- ▶ via some integral inequalities  $\rightsquigarrow$  the equality sign in the generalized Newton's ineq:  $S_2(W) \leq \frac{N-1}{2N} tr(W)^2$  holds
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- via some integral inequalities → the equality sign in the generalized Newton's ineq: S<sub>2</sub>(W) ≤ N-1/2N tr(W)<sup>2</sup> holds → W = λId
- hence D<sup>2</sup>v = λ(∇<sup>2</sup><sub>ξ</sub>V(Dv))<sup>-1</sup> → M<sub>H</sub>(Ω) is constant →Ω is Wulff shape (by the anisotropic Alexsandrov Theorem).

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$$\begin{cases} \Delta_p^H u = 0 & \text{ in } \mathbb{R}^N \setminus \overline{\Omega} \\ u = 1 & \text{ on } \partial\Omega, \\ H(Du) = C & \text{ on } \partial\Omega, \\ u \to 0 & \text{ if } |x| \to \infty. \end{cases}$$

Auxiliary problem: for  $v(x) = u^{\frac{p}{p-N}}$ 

$$\begin{cases} \Delta_p^H v = N \frac{p-1}{p} \frac{H^p(Dv)}{v} & \text{ in } \mathbb{R}^N \setminus \overline{\Omega} \\ v = 1 & \text{ on } \partial\Omega \\ H(Dv) = \frac{p}{N-p}C & \text{ on } \partial\Omega, \\ v \to +\infty & \text{ if } |x| \to \infty \end{cases}$$

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 $\text{let } V(\xi) = \frac{1}{\rho} H^{\rho}(\xi). \ W = \nabla_{\xi}^{2} V(Dv) D^{2}v \rightsquigarrow \Delta_{\rho}^{H}v = Tr(W).$ 

► Step I: 
$$C = \frac{N-p}{N(p-1)} \frac{P_H(\Omega)}{|\Omega|};$$

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let  $V(\xi) = \frac{1}{p}H^{p}(\xi)$ .  $W = \nabla_{\xi}^{2}V(Dv) D^{2}v \rightsquigarrow \Delta_{p}^{H}v = Tr(W)$ .  $\mathbf{Step I:} \ C = \frac{N-p}{N(p-1)} \frac{P_{H}(\Omega)}{|\Omega|};$ 

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**Step II:** Newton's Inequality for *W*: 2  $S_2(W) \le \frac{N-1}{N}(Tr(W))^2$ , where

$$2S_2(W) = S_{ij}^2(W)V_{\xi_i\xi_k}v_{kj} \quad \text{and} \quad S_{ij}^2W = \begin{cases} -V_{\xi_j\xi_k}v_{ki} & \text{if } i \neq j \\ -V_{\xi_j\xi_k}v_{ki} + \Delta_p^Hv & \text{if } i = j. \end{cases}$$

recall:  $tr(W) = \Delta_p^H v \rightsquigarrow$  by Newton ineq:  $0 \ge 2v^{\gamma}S_2(W) - \frac{N-1}{N}v^{\gamma}(\Delta_p^H v)^2 = div(*) - v^{\gamma-2}H^{2p}(Dv)(P(\gamma)).$ 

 $\rightsquigarrow$  for  $\gamma = 1 - N$  we have  $P(\gamma) = 0$  and hence  $div(*) \le 0$  that is

$$div(v^{1-N}S^2_{ij}(W)V_{\xi_i} - (N-1)(p-1)v^{-N}V(Dv)\nabla_{\xi}V(Dv)) \leq 0,$$
  
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**Step III:** By the Divergence Theorem, the fact that  $v = \frac{Dv}{|Dv|}$  on  $\partial\Omega$ , the definition of  $S_{ii}^2(W)$ , the homogeneity of  $H(\xi)$  and the fact that

$$\begin{split} \Delta_{\rho}^{H} v &= (p-1)H^{p-2}H_{\xi_{k}}H_{\xi_{l}}v_{kl} + H^{p-1}M_{H},\\ \text{it holds } \int_{\partial\Omega}H(v)H^{2(p-1)}(Dv)\Big(\frac{M_{H}(\partial\Omega)}{N-1} - \frac{p-1}{p}\frac{H(Dv)}{v}\Big) \ d\sigma \geq 0. \end{split}$$

→NOTICE: with H(Du) = C on  $\partial \Omega$  and Step I, we have

$$\int_{\partial\Omega} H(\nu) \frac{\mathsf{M}_H(\partial\Omega)}{N-1} \geq \frac{P_H^2(\Omega)}{N|\Omega|}.$$

This is the reverse of Minkowski inequality ---- equality holds.

**Step IV:**  $\rightsquigarrow$ equality holds in Newton's inequality for  $W = \nabla_{\varepsilon}^2 V(Dv(x)) D^2 v(x)$  that is  $W = \gamma(x) l$ .

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it holds  $\int_{\partial\Omega} H(\mathbf{v})H^{2(p-1)}(D\mathbf{v})\left(\frac{\mathbf{M}_{H}(\partial\Omega)}{N-1} - \frac{p-1}{p}\frac{H(D\mathbf{v})}{\mathbf{v}}\right) d\sigma \ge 0.$ 

→NOTICE: with H(Du) = C on  $\partial \Omega$  and Step I, we have

$$\int_{\partial\Omega} H(v) \frac{\mathsf{M}_H(\partial\Omega)}{\mathsf{N}-1} \geq \frac{\mathsf{P}_H^2(\Omega)}{\mathsf{N}|\Omega|}.$$

This is the reverse of Minkowski inequality  $\rightsquigarrow$  equality holds.

**Step IV:**  $\rightsquigarrow$  equality holds in Newton's inequality for  $W = \nabla_{\mathcal{E}}^2 V(Dv(x)) D^2 v(x)$  that is  $W = \gamma(x) l$ .

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**Step V:**  $\exists \lambda \in \mathbb{R}^+$ :  $W = \lambda I \rightsquigarrow D^2 v = \lambda (\nabla_{\varepsilon}^2 V)^{-1}$ 

**Step VI:** by the definition of the anisotropic mean curvature we obtain:

$$\mathsf{M}_{H}(\partial\Omega) = H_{\xi_i\xi_j}(Dv)v_{ij} = \lambda H_{\xi_i\xi_j}[(\nabla_{\xi}^2 V)^{-1}]_{ij} = \tilde{c}H^{2-p}(Dv)$$

 $\rightsquigarrow M_H(x)$ = constant  $\rightsquigarrow \Omega$  is Wulff shape,  $\Omega = rB_{H_0}$ . q.e.d.

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# Anisotropic overdetermined capacitary problem:

 $\Omega \longrightarrow$  conductor  $u_{\Omega} \longrightarrow$  electrostatic potential  $H(Du_{\Omega}) \longrightarrow$  norm of the field;

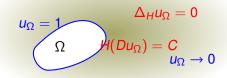


 $\rightsquigarrow$ An electrical conductor  $\Omega$  while embedded in an anisotropic dielectric and maintaining a given potential energy has constant intensity of the electrostatic field on its boundary if and only if it is an anisotropic ball.. The same holds in the case of power-type conductivity laws.

> [W. Reichel 1997  $H(\cdot) = |\cdot|]$ [CB, G. Ciraolo, P. Salani, 2016 p = 2] [CB, L. Brasco, G. Ciraolo preprintp < N]

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This technique has been adapted to other situations:

- in the case of other integral constraints (involving geometric quantities as M<sub>H</sub>, the capacity...);
- ► for Serrin interior problem for the Finsler *p*-Laplacian.

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