

# On the optimization of traffic flow at a junction

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Contrôle des EDP et Applications

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Joint research with A. Cesaroni, G.M. Coclite, M. Garavello



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DI PADOVA

# The LWR traffic flow model (1955, 1956)

*A new problem, which has arisen in the twentieth century, is how to organize road traffic so that the full benefits of our increased mobility can be enjoyed at the lowest cost in human life and capital. The problem has many sides - constructional, legal, educational, administrative. - M.J. Lighthill, G.B. Whitham (1955)*

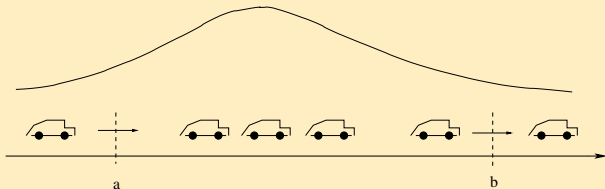
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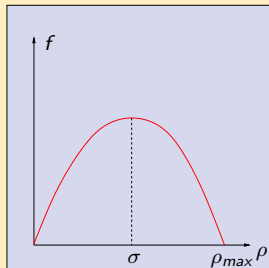
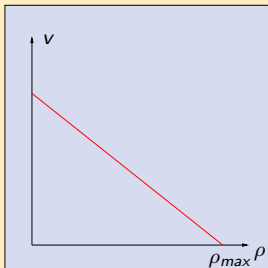
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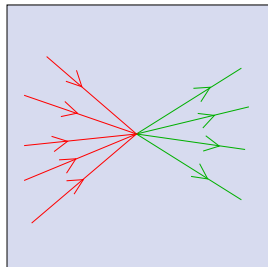
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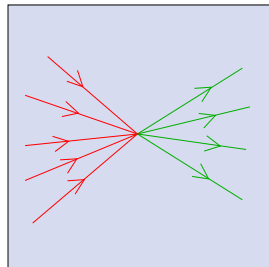
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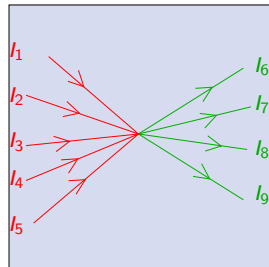
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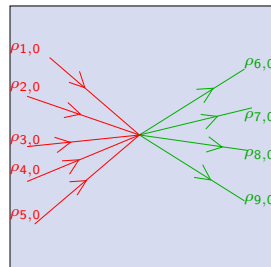
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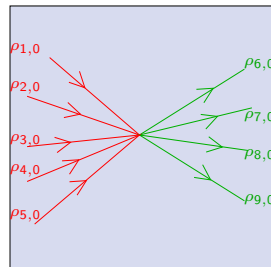


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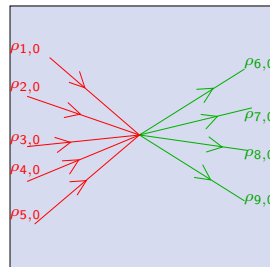


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- Coupling transition condition at the node

$$\Psi(\rho_1(t, 0), \dots, \rho_{m+n}(t, 0)) = 0$$

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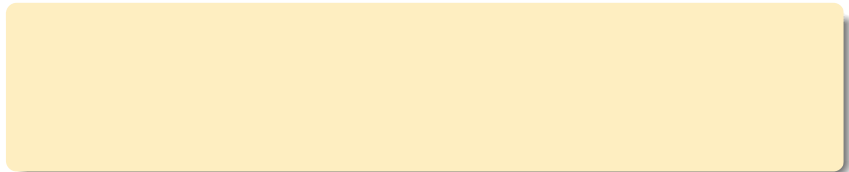
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Achdou, Andreianov, Banda, Bastin, Bressan, Camilli, Canic, Coclite, Colombo, Coron, Costeseque, D'Apice, Donadello, Garavello, Gasser, Goatin, Göttlich, Gugat, Han, Herty, Holden, Imbert, Klar, Lattanzio, Lebacque, Leugering, Manzo, Marchi, Monneau, Moutari, Nguyen, Marigo, Piccoli, Rascle, Risebro, Rosini, Schleper, Shen, Tchou, Zidani, Ziegler...



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$$0 \leq a_{ji}(t) \leq 1 \quad \forall j, i \quad \sum_{j=m+1}^{m+n} a_{ji}(t) = 1 \quad \forall i$$

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(when  $m > n$  and the total possible flux on the incoming roads is larger than the maximal flux that the outgoing roads can handle)

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- **Junction Riemann Solver (JRS)**: provide nodal conditions and a procedure for (uniquely) solving  $m + n$  IBV problems at  $m$  incoming and  $n$  outgoing roads when initial data are constants. Solutions are self-similar as for classical Riemann problems.

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**Remark:** the definition of **JRS determines all** features of **possible solutions** at the junction.

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A **Riemann solver** at the node is a map

$$\begin{aligned} \mathcal{RS} : [0, \rho_{\max}]^{m+n} &\rightarrow [0, \rho_{\max}]^{m+n}, \\ (\rho_{0,1}, \dots, \rho_{0,m+n}) &\mapsto (\tilde{\rho}_1, \dots, \tilde{\rho}_{m+n}) \end{aligned}$$

that associates to an  $(m+n)$ -tuple of constant **initial data** an  $(m+n)$ -tuple of constant **boundary data** which are the traces at the node of the solution to the corresponding Riemann problem.

# Junction Riemann Solver ... contin'd

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## Algorithm

- $\Omega = \left\{ (\gamma_1, \dots, \gamma_n) \in \prod_{i=1}^n \Omega_i : A \cdot (\gamma_1, \dots, \gamma_n)^T \in \prod_{j=n+1}^{n+m} \Omega_j \right\}$
- Maximize  $E = \gamma_1 + \dots + \gamma_n$  on  $\Omega$
- Find the corresponding densities
- Select the densities that satisfy the priority rules

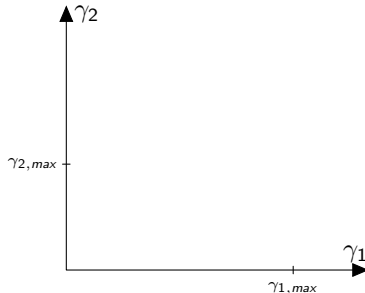
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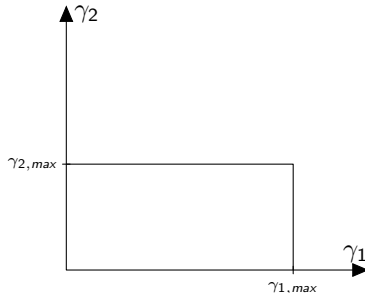
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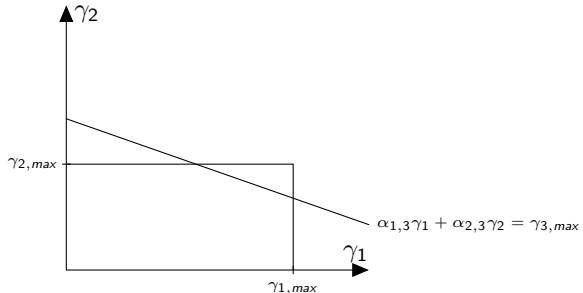
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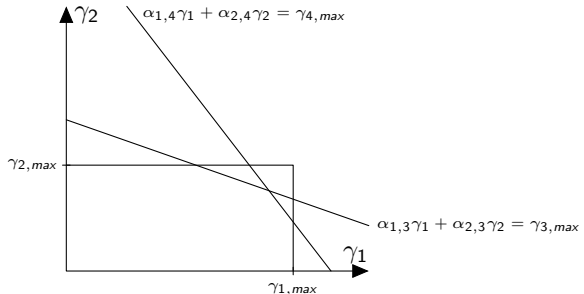
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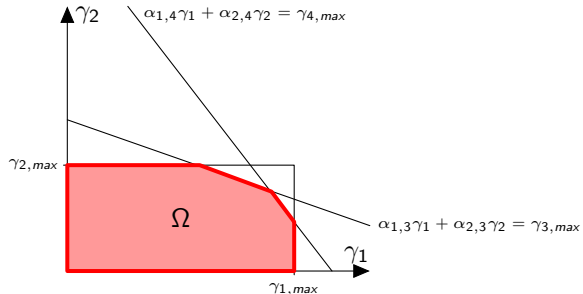
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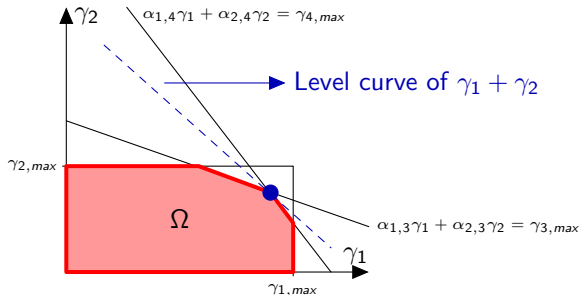
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## A different approach: a control theoretic point of view

Fix  $T > 0$ . Find the solution on  $[0, T]$  to the Cauchy problem

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that satisfies the flux constraint

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and **maximizes** an integral cost

$$\int_0^T \sum_{l=1}^n f(\rho_l(t, 0)) dt$$

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$$\begin{cases} \partial_t \rho_l + \partial_x f(\rho_l) = 0, & x \in I_l, l \in \{1, \dots, n+m\}, t > 0 \\ \rho_l(0, x) = \rho_{0,l}(x), & x \in I_l, l \in \{1, \dots, n+m\}, \end{cases}$$

that satisfies the flux constraint

$$A \cdot (f(\rho_1(t, 0)), \dots, f(\rho_m(t, 0)))^T = (f(\rho_{m+1}(t, 0)), \dots, f(\rho_{m+n}(t, 0)))^T$$

and **maximizes** an integral cost

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- The maximization is **global** on  $[0, T]$  among **all admissible solutions** (fulfilling linear flux constraints) and not pointwise in time among all admissible self-similar solutions of the Riemann problems

Given initial data  $\bar{\rho}_l : \mathbb{R} \rightarrow [0, \rho_{\max}]$ ,  $l \in \{1, \dots, m+n\}$ ,

- .



- For  $l \in \{1, \dots, m\}$ ,  $I_l = (-\infty, 0]$  (incoming arcs)

$$\begin{cases} \partial_t \rho_l + \partial_x f(\rho_l) = 0 & x < 0, t > 0 \\ \rho_l(0, x) = \bar{\rho}_l(x) & x < 0 \\ \rho_l(t, 0) = \tilde{\rho}_l(x) & t > 0 \end{cases}$$

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$$\mathcal{F}_l^M = \mathcal{F}_l^M(\bar{\rho}_l) \doteq \left\{ f(\rho_l(\cdot, 0)) \in \mathcal{F}_l \mid \text{T.V.}(\rho_l(\cdot, 0)) \leq M \right\}$$

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- For  $l \in \{m+1, \dots, m+n\}$ ,  $I_l = [0, +\infty)$  (outgoing arcs)

$$\begin{cases} \partial_t \rho_l + \partial_x f(\rho_l) = 0 & x > 0, t > 0 \\ \rho_l(0, x) = \bar{\rho}_l(x) & x > 0 \\ \rho_l(t, 0) = \tilde{\rho}_l(x) & t > 0 \end{cases}$$

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- . Admissible flux traces

$$\mathcal{G} = \left\{ (g_1, \dots, g_m) \in \prod_{i=1}^m \mathcal{F}_i : \sum_{i=1}^m \alpha_{ji} g_i \in \mathcal{F}_j, j = m+1, \dots, m+n \right\}$$

$$\mathcal{G}^M = \left\{ (g_1, \dots, g_m) \in \prod_{i=1}^m \mathcal{F}_i^M : \sum_{i=1}^m \alpha_{ji} g_i \in \mathcal{F}_j, j = m+1, \dots, m+n \right\}$$

# Existence of optimal solutions

Theorem (A., Cesaroni, Coclite, Garavello)

Let  $\mathcal{J} : \mathbb{R}^n \rightarrow \mathbb{R}$  be a continuous map. For every  $M > 0$ , there exists  $\hat{g} \in \mathcal{G}^M$  such that

$$\int_0^T \mathcal{J}(\hat{g}(t)) dt = \sup_{g \in \mathcal{G}^M} \int_0^T \mathcal{J}(g(t)) dt$$

Ex:  $\mathcal{J}(g_1, \dots, g_m) = \sum_i g_i, \quad \mathcal{J}(g_1, \dots, g_m) = \prod_i g_i,$

Proof:

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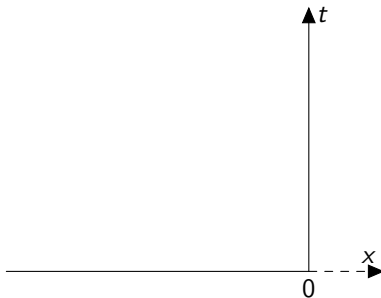
- Uniform BV bounds and Helly's compactness theorem  
 $\implies$  convergence of subsequence of flux traces
- Divergence theorem on  $[-\max |f'(\rho)| \cdot T, 0] \times [0, T]$   
 $\implies$  convergence of flux traces of solutions to flux trace of limit solution

## Remark on boundary data for conservation laws

$$\begin{cases} \partial_t \rho + \partial_x \rho = 0 & x \in (-\infty, 0), \quad t > 0, \\ \rho(0, x) = \bar{\rho}(x) & x \in (-\infty, 0) \\ \rho(t, 0) = \tilde{\rho}(t) & t > 0 \end{cases}$$

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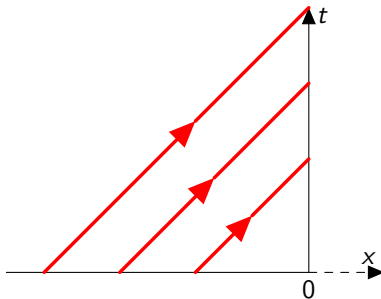
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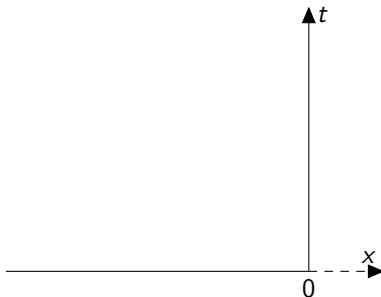


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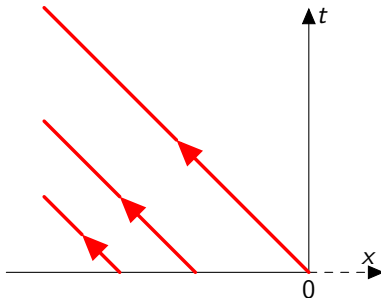
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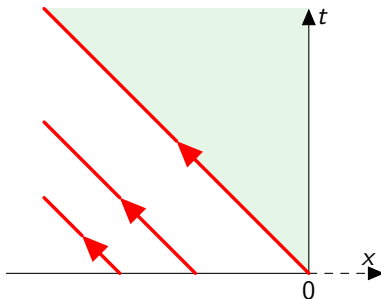
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# Case $n = m = 1$ : comparison with entropy solution of CP



$$\begin{cases} \partial_t \rho_1 + \partial_x f(\rho_1) = 0 & x < 0, t > 0, \\ \rho_1(0, x) = \bar{\rho}_1(x) & x < 0, \end{cases} \quad \begin{cases} \partial_t \rho_2 + \partial_x f(\rho_2) = 0 & x > 0, t > 0 \\ \rho_2(0, x) = \bar{\rho}_2(x) & x > 0, \end{cases}$$

$$\mathcal{G} = \mathcal{F}_1 \cap \mathcal{F}_2$$

$$\mathcal{G}^M = \mathcal{F}_1^M \cap \mathcal{F}_2$$

$$\sup_{g \in \mathcal{G}^M} \int_0^T \mathcal{J}(g(t)) dt \quad (max)_M$$

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Incoming road

Outgoing road

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$$\mathcal{F}_1 \doteq \left\{ f(\rho_1(\cdot, 0)) \mid \rho_1 \text{ sol on } [0, T] \times (-\infty, 0], \tilde{\rho}_1(t) \in [0, \rho_{\max}] \right\},$$

$$\mathcal{F}_2 \doteq \left\{ f(\rho_2(\cdot, 0)) \mid \rho_2 \text{ sol on } [0, T] \times [0, +\infty), \tilde{\rho}_2(t) \in [0, \rho_{\max}] \right\},$$

$$\mathcal{F}_l^M \doteq \left\{ f(\rho_l(\cdot, 0)) \in \mathcal{F}_l \mid \text{T.V.}(\rho_l(\cdot, 0)) \leq M \right\}, \quad l = 1, 2.$$

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## Cauchy problem on $\mathbb{R}$

$$\begin{cases} \partial_t \rho + \partial_x f(\rho) = 0 \\ \rho(0, x) = \begin{cases} \bar{\rho}_1(x) & \text{if } x < 0 \\ \bar{\rho}_2(x) & \text{if } x > 0 \end{cases} \end{cases} \quad (\text{CP})$$

$$\left. \begin{array}{l} \rho_e : [0, T] \times \mathbb{R} \rightarrow \mathbb{R} \text{ entropy admissible sol. to (CP)} \\ \text{T.V.}(\rho_e(\cdot, 0)) \leq M \end{array} \right\} \implies \rho_e(\cdot, 0) \in \mathcal{G}^M.$$



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Consider  $\mathcal{J}(g) = g$

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For every  $T > 0$ , the entropy admissible solution  $\rho_e$  to (CP) solves the maximization problem  $(\max)_M$ , i.e.

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for every  $M \geq \text{T.V.}(\rho_e(\cdot, 0))$ .

The proof relies on Hopf-Lax formula for explicit representation of viscosity solutions to IBV for Hamilton-Jacobi equation

$$\rho(t, x) \text{ entropy weak sol'n of } \partial_t \rho + \partial_x (f(\rho)) = 0$$

$\Downarrow$

$$v(t, x) \doteq \text{viscosity sol'n of } \partial_t v + f(\partial_x v) = 0$$

# Case $n = m = 1$ : non entropic optimal solutions



$$f(\rho) = \rho(1 - \rho)$$

$$\begin{cases} \partial_t \rho_1 + \partial_x (\rho_1(1 - \rho_1)) = 0 \\ \rho_1(0, x) = \frac{1}{4} \end{cases} \quad \begin{cases} \partial_t \rho_2 + \partial_x (\rho_2(1 - \rho_2)) = 0 \\ \rho_2(0, x) = \frac{1}{4} \end{cases}$$

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The functions

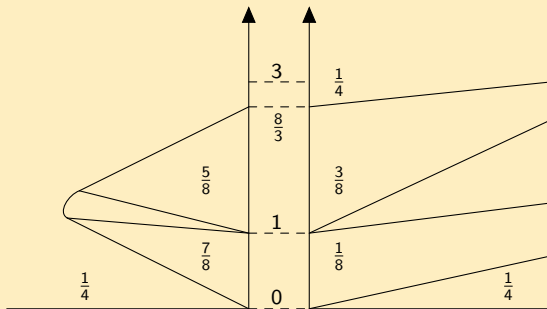
$$\rho_1(t, x) \equiv \frac{1}{4} \quad \rho_2(t, x) \equiv \frac{1}{4}$$

provide an optimal solution, i.e.

$$\frac{3}{16} T = \int_0^T f(\rho_1(t, 0)) dt = \sup_{g \in \mathcal{G}^M} \int_0^T g(t) dt$$

# Case $n = m = 1$ : non entropic optimal solutions

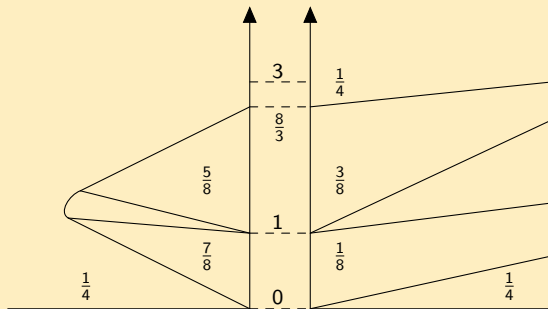
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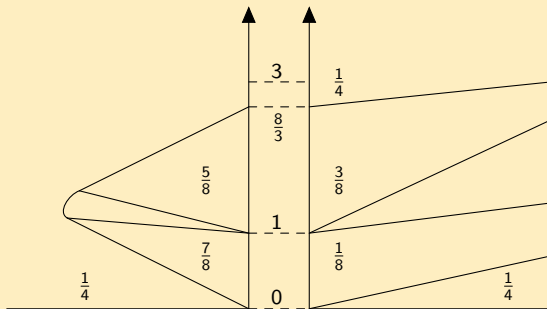


provide another optimal solution.

$$\int_0^T f(\rho(t, 0)) dt = f\left(\frac{7}{8}\right) \cdot 1 + f\left(\frac{5}{8}\right) \cdot \frac{5}{3} + f\left(\frac{1}{4}\right) \cdot \left(T - \frac{8}{3}\right)$$

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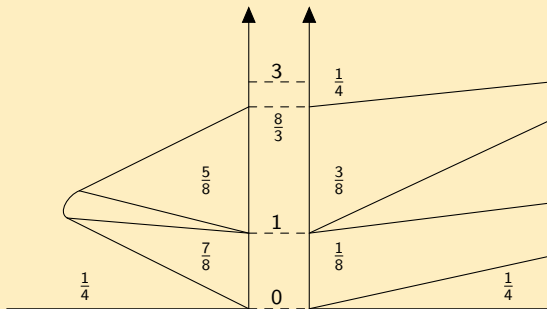
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$$\int_0^T f(\rho(t, 0)) dt = \frac{7}{64} + \frac{15}{64} \cdot \frac{5}{3} + \frac{3}{16} \cdot \left(T - \frac{8}{3}\right)$$



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# Additional optimization criterion

Fix  $T, M > 0$ . In connection with the nodal problem

$$\begin{cases} \partial_t \rho_l + \partial_x f(\rho_l) = 0, & l \in \{1, \dots, m+n\} \\ \rho_l(0, x) = \rho_{0,l}(x), \end{cases}$$

with flux constraints

$$A \cdot (f(\rho_1(t, 0)), \dots, f(\rho_m(t, 0)))^T = (f(\rho_{n+1}(t, 0)), \dots, f(\rho_{m+n}(t, 0)))^T$$

and  $\mathcal{G}^M$  set of admissible flux traces as above, let  $\mathcal{D}_M$  denote the set of **optimal solutions** of

$$\sup_{g \in \mathcal{G}^M} \int_0^T \mathcal{J}(g(t)) dt \quad (\max)_M$$

Then minimizes

$$\min_{g \in \mathcal{D}_M} \sum_{i=1}^m \text{T.V.}_{(0,T)} g_i(\cdot). \quad (\min)_M$$

## Additional criterium: existence of solution

Theorem (A.,Cesaroni, Coclite, Garavello)

Let  $\mathcal{J} : \mathbb{R}^n \rightarrow \mathbb{R}$  be a continuous map. For every  $M > 0$ , there exists  $\hat{g} \in \mathcal{G}^M$  such that

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**Notice:** solutions of the min-max problems fulfills the requirement of maximize the total flux through the junction keeping the oscillation the smallest possible

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Consider  $\mathcal{J}(g) = g$

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Theorem (A., Cesaroni, Coclite, Garavello)

For every  $T > 0$ , let  $\rho_e$  be the entropy admissible solution to (CP) and assume that  $\rho_e(\cdot, 0)$  is monotone. Then  $\rho_e \rho_e(\cdot, 0)$  solves the minmax problem  $(\min)_M$ , i.e.

$$\text{T.V.}_{(0,T)} = \min_{g \in \mathcal{D}^M} \text{T.V.}_{(0,T)} g(\cdot)$$

for every  $M \geq \text{T.V.}(\rho_e(\cdot, 0))$ .

Merci de votre attention!