

Concentration sets for multiple equal depth wells potentials in the 2D elliptic case

Fabrice Bethuel

Laboratoire Jacques-Louis Lions,
Université Pierre et Marie Curie – Paris 6

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The equations

The limiting behavior as $\varepsilon \rightarrow 0$ of solutions to the reaction-diffusion equations of the type

$$\frac{\partial u}{\partial t} - \Delta u_\varepsilon = -\varepsilon^{-2} \nabla V_u(u_\varepsilon)$$

is a source of *active research* in the last decades. The function u_ε takes values in \mathbb{R}^k and V denotes a potential $V: \mathbb{R}^k \rightarrow \mathbb{R}$. Of interest are also the *stationary solutions* we will discuss later on

$$-\Delta u_\varepsilon = -\varepsilon^{-2} \nabla V_u(u_\varepsilon).$$

The equation is the L^2 gradient-flow of the **energy** \mathcal{E} defined by

$$E_\varepsilon(u) = \int_{\Omega} e_\varepsilon(u) = \int_{\mathbb{R}} \varepsilon \frac{|\nabla u|^2}{2} + \frac{V(u)}{\varepsilon}, \text{ for } u : \mathbb{R} \mapsto \mathbb{R}^k.$$

$\Omega \subset \mathbb{R}^N$ being the domain. The properties of the flow (*RDG*) strongly depend on the **potential** V . Throughout we assume that

- V is **smooth** from \mathbb{R}^k to \mathbb{R} ,
- V tends to infinity at infinity, so that it is **bounded below**

$$V \geq 0.$$

An **intuitive guess** is that the flow drives to **mimimizers of the potential** :

- if V is **strictly convex**, the solution should tend to the **unique minimizer** of the potential V .
- Here we consider the case where there are **several mimimizers for the potential** $V \rightsquigarrow$ **Transitions between minimizers**

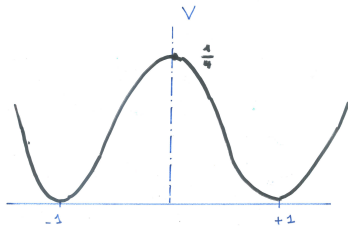
Multiple-well potentials

We assume in this talk that V has a **finite number** of and at least **two distinct minimizers**.

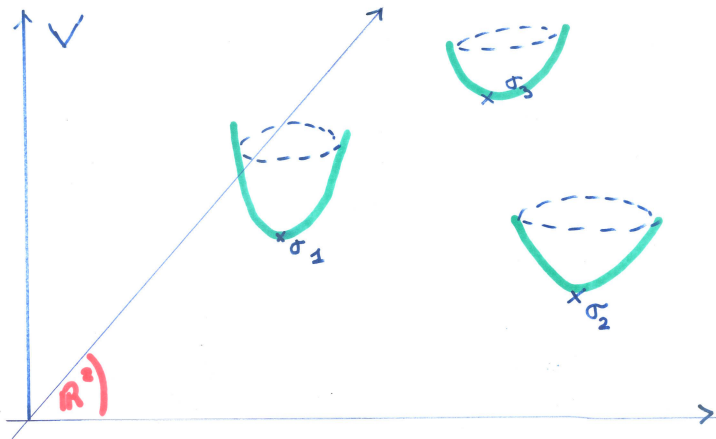
A **classical example** in the scalar case (**Allen-Cahn**) $k = 1$

$$V(u) = \frac{(1 - u^2)^2}{4}, \quad (\text{AC})$$

whose minimizers are $+1$ and -1 .



The picture for systems



Assumptions on V

(H₁) $\inf V = 0$ and the set of minimizers $\Sigma \equiv \{y \in \mathbb{R}^k, V(y) = 0\}$

is a finite set, with **at least two** distinct elements, that is

$$\Sigma = \{\sigma_1, \dots, \sigma_q\}, q \geq 2, \sigma_i \in \mathbb{R}^k, \forall i = 1, \dots, q.$$

(H_∞) There exists constant $\alpha_0 > 0$ and $R_0 > 0$ such that

$$y \cdot \nabla V(y) \geq \alpha_0 |y|^2, \text{ if } |y| > R_0.$$

The scalar case

Important efforts have been devoted so far to the study of solutions of the *Allen-Cahn equations*, i.e. for the special choice of potential

$$V(u) = \frac{(1 - u^2)^2}{4}, \quad (2)$$

whose infimum equals 0 and whose minimizers are $+1$ and -1 , so that $\Sigma = \{+1, -1\}$. It is an elementary model for *phase transitions* for materials with *two equally preferred states*, the minimizers $+1$ and -1 of V .

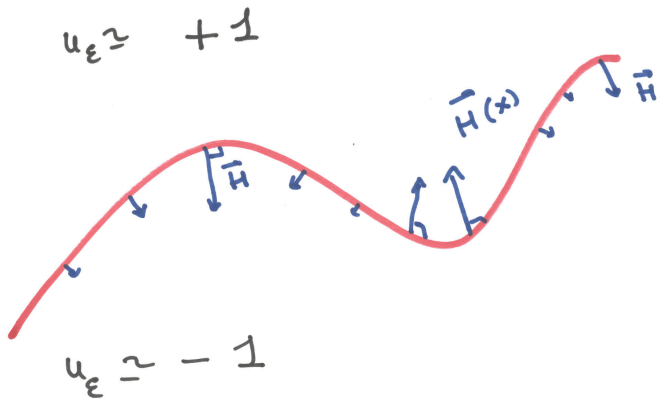
The mathematical theory for this question is now well advanced and may be considered as **quite satisfactory**.

Results for the scalar case

They provide a **sound foundation to the intuitive idea** that the domain Ω decomposes into regions where the solution takes values **close to +1** or **close to -1**, separated by interfaces of **width of order ε** .

- The interfaces converge to **codimension 1** hypersurfaces.
- They are **generalized minimal surfaces** in the stationary case, or **moved by mean curvature** for the parabolic case.
- Arguments rely on **integral methods** and **energy estimates**
- **In the parabolic case Ilmanen** proved convergence past **possible singularities**, to motion by mean curvature in the **weak sense of Brakke**, a notion phrased in the language of **geometric measure theory**.
- In the elliptic case convergence to minimal surfaces was established by **Modica and Mortola** for minimizers, **Hutchinson and Tonegawa** established related results for non-minimizing solutions.
- The fact that the solutions are **scalar** is crucial in the proofs.

motion by mean curvature



Monotonicity Formula and Clearing-out

Concentration on $N - 1$ dimensional sets is deduced from two ingredients

- Monotonicity formulas
- Clearing-out Lemmas

The following inequality (used in Ginzburg-Landau theory)

$$\frac{d}{dr} \left(\frac{1}{r^{N-2}} E_{\varepsilon} \left(u_{\varepsilon}, \mathbb{B}^N(x_0, r) \right) \right) \geq 0, \text{ for any } x_0 \in \Omega,$$

is valid for arbitrary vectorial potentials. It is however not sufficient to establish concentration on $N - 1$ - dimensional sets where one wishes to have

$$\frac{d}{dr} \left(\frac{1}{r^{N-1}} E_{\varepsilon} \left(u_{\varepsilon}, \mathbb{B}^N(x_0, r) \right) \right) \geq 0, \text{ for any } x_0 \in \Omega, \quad (3)$$

Such a formula was derived in the Allen-Cahn scalar case thanks to the maximum principle.

The discrepancy

The proof of the $N-1$ monotonicity in the scalar case relies the positivity of the discrepancy term

$$\xi_\varepsilon(u_\varepsilon) = \frac{1}{\varepsilon} V(u_\varepsilon) - \varepsilon \frac{|\nabla u|^2}{2}.$$

Notice that for $N=1$ for $-\varepsilon^2 \frac{d^2 u}{dx^2} = -\nabla_u V(u)$ one has

$$\frac{d}{dx} \left(\frac{1}{\varepsilon} V(u) - \varepsilon \frac{|\dot{u}|^2}{2} \right) = 0,$$

In higher dimensions, the positivity of ξ_ε for scalar solutions was observed first by Payne, Sperb, L. Modica,... for entire solutions. He proved the remarkable inequality (for $\varepsilon=1$)

$$-|\nabla u|^2 \Delta \xi \geq 2 \frac{1}{2} |\nabla \xi|^2 + 2V(u) \nabla u \cdot \nabla \xi_\varepsilon.$$

Clearing-out lemmas

Clearing-out Lemmas have more or less the **following flavour** : There exists some constant $\eta_0 > 0$ such that

$$\frac{1}{r^{N-1}} E_\varepsilon \left(u_\varepsilon, \mathbb{B}^N(x_0, r) \right) \leq \eta_0 \implies u_\varepsilon(x) \simeq \sigma \text{ on } \mathbb{B}^N \left(x_0, \frac{r}{2} \right).$$

where $\sigma \in \Sigma$, the set of minimizers of the potential.
 Such a statement is rather easy to prove when monotonicity is established.
 Indeed, by monotonicity

$$\frac{1}{\varepsilon^N} \int_{\mathbb{B}^N(\varepsilon)} V(u_\varepsilon) \leq \eta_0.$$

and then the (easy) bound $|\nabla u_\varepsilon| \leq C\varepsilon^{-1}$ allows to conclude.

Tools in the scalar Allen-Cahn case

To summarize the methods used in the scalar Allen-Cahn case one has

sign of discrepancy \Rightarrow monotonicity \Rightarrow clearing-out

whereas

$\left\{ \begin{array}{l} \text{clearing out} + \text{monotonicity} \Rightarrow \text{concentration on } N-1 \text{ dimensional sets} \\ \text{monotonicity} \Rightarrow (\text{Preiss}) \text{ rectifiability of concentration set} \end{array} \right.$

and

sign of discrepancy + stress-energy tensor

\Downarrow

stationary sets or motion by mean-curvature

Conclusion: Sign of discrepancy is crucial !

Back to the vectorial case

Main observation

In the **vectorial case**, **positivity of the discrepancy** as well as the **monotonicity formula** are known to fail for some solutions, e. g. for the **Ginzburg-Landau system**. Whether they might still hold under **additional conditions** on the potential or the solution itself is open.



New ideas are required !

I will next present a result where some parts of the program have been carried out in the absence of **monotonicity** as well as **sign of discrepancy**. It concerns

- the **two-dimensional case**, i. e. we work on a **domain** $\Omega \subset \mathbb{R}^2$
- The elliptic system

The assumptions

Assume we are given a constant $M_0 > 0$ and a family $(u_\varepsilon)_{0 < \varepsilon \leq 1}$ of solutions to the equation

$$-\Delta u_\varepsilon = \nabla V_u(u_\varepsilon) \quad \text{on } \Omega.$$

satisfying the natural energy bound

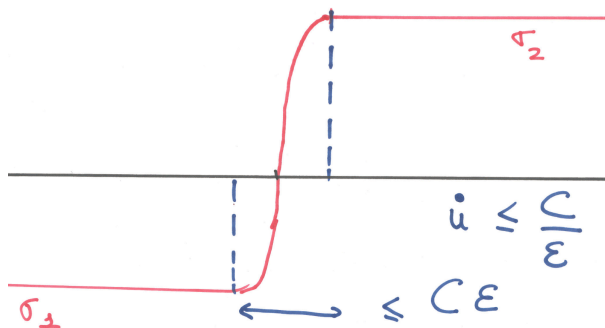
$$E_\varepsilon(v_\varepsilon) \leq M_0, \quad \forall \varepsilon > 0. \quad (4)$$

Remark : This bound is natural because the energy of one-dimensional transition, i. e. solutions

$$-\ddot{u} = \varepsilon^{-2} \nabla v_u(u)$$

is finite, bounded independently of ε .

Energy of an interface



$$\begin{cases} \int_{\mathbb{R}} |\dot{u}|^2 \simeq C^2 \int_{[-C\epsilon, C\epsilon]} \epsilon^{-2} \simeq C\epsilon^{-1} \\ \int_{\mathbb{R}} |V(u)|^2 \simeq C \int_{[-C\epsilon, C\epsilon]} \simeq C\epsilon \end{cases}$$

Limiting measures

We introduce the family $(\nu_\varepsilon)_{0 < \varepsilon \leq 1}$ of measures defined on Ω

$$\nu_\varepsilon \equiv e_\varepsilon(u_\varepsilon) dx \text{ on } \Omega. \quad (5)$$

In view of the energy bound, the total mass of the measures is bounded by M_0 , that is $\nu_\varepsilon(\Omega) \leq M_0$. By compactness, there exists a decreasing subsequence $(\varepsilon_n)_{n \in \mathbb{N}}$ tending to 0 and a limiting measure ν_\star on Ω such that

$$\nu_{\varepsilon_n} \rightarrow \nu_\star \text{ in the sense of measures on } \Omega \text{ as } n \rightarrow +\infty. \quad (6)$$

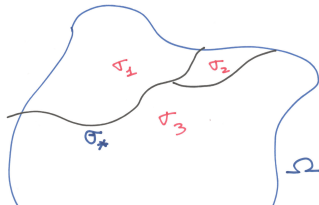
Our main result is the following.

Theorem

There exist a subset \mathcal{G}_\star in Ω , and a subsequence of $(\varepsilon_n)_{n \in \mathbb{N}}$ still denoted $(\varepsilon_n)_{n \in \mathbb{N}}$ such that the following properties hold:

- i) \mathcal{G}_\star is a **closed 1-dimensional rectifiable**, with **locally finite many connected components** and such that $\mathcal{H}^1(\mathcal{G}) \leq C_H M_0$, where C_H is a constant depending only on the potential V .
- ii) Set $\mathcal{U}_\star = \Omega \setminus \mathcal{G}_\star$, and $(\mathcal{U}_\star^i)_{i \in I}$ be the connected components of \mathcal{U}_\star . For each $i \in I$ there exists an element $\sigma_i \in \Sigma$ such that

$$u_\varepsilon \rightarrow \sigma_i \text{ uniformly on every compact subset of } \mathcal{U}_\star^i.$$



Comments on the results

- At this stage, I have not been able to prove **stationary**, nor **positivity of discrepancy**.
- The set \mathfrak{S}_\star in the above theorem represents the concentration set for the energy
- The argument for the **proof of rectifiability** of the singular set \mathfrak{S}_\star is quite specific , namely **compact set of hausdorff dimension 1 are rectifiable**.
- Most of the statement relies on the two clearing-out properties which follow :

Clearing-out properties for the measure ν_\star

The first one is a classical clearing-out result for the measure ν_\star .

Theorem

Let $x_0 \in \Omega$ and $r > 0$ be given such that $\mathbb{D}^2(x_0, r) \subset \Omega$. There exists a constant $\eta_0 > 0$ such that, if we have

$$\frac{\nu_\star(\overline{\mathbb{D}^2(x_0, r)})}{r} < \eta_0, \text{ then it holds } \nu_\star\left(\overline{\mathbb{D}^2(x_0, \frac{r}{2})}\right) = 0. \quad (7)$$

we set

$$\theta_\star(x_0) = \liminf_{r \rightarrow 0} \frac{\nu_\star(\overline{\mathbb{D}^2(x_0, r)})}{r}$$

and define \mathfrak{S}_\star as

$$\mathfrak{S}_\star = \{x \in \Omega, \theta_\star(x_0) \geq \eta_0\}. \quad (8)$$

The fact that \mathfrak{S}_\star is closed of finite one-dimensional Hausdorff measure is a direct consequence of the clearing-out property for the measure ν_\star .

The connectedness properties of \mathfrak{S}_\star require a different type of clearing-out result. Let $\mathcal{U} \subset \Omega$ be open. For $\delta > 0$, we consider the sets

$$\begin{cases} \mathcal{U}_\delta = \{x \in \Omega, \text{dist}(x, \mathcal{U}) \leq \delta\} \text{ and} \\ \mathcal{V}_\delta = \mathcal{U}_\delta \setminus \mathcal{U} = \{x \in \Omega, 0 \leq \text{dist}(x, \mathcal{U}) \leq \delta\}. \end{cases} \quad (9)$$

Theorem

Let $\mathcal{U} \subset \Omega$ be a open subset of Ω , let $\delta > 0$ be given. If we have

$$\nu_\star(\mathcal{V}_\delta) = 0, \text{ then it holds } \nu_\star(\overline{\mathcal{U}}) = 0. \quad (10)$$

In other terms, if the measure ν_\star vanishes in some neighborhood of the set \mathcal{U} , then it vanishes on $\overline{\mathcal{U}}$.

- allows us to establish the **connectedness properties** of \mathfrak{S}_\star .
- yields **rectifiability** invoking standard results on continua of bounded one-dimensional Hausdorff measure.

Elements in the proof : 1) scale invariance

Proofs are derived from corresponding PDE results at the ε level for u_ε .

For $r > 0$ and $\varepsilon > 0$, set $\varepsilon = \frac{\varepsilon}{r}$. For $u_\varepsilon : \mathbb{D}^2(x_0, r) \rightarrow \mathbb{R}^k$, consider $v_\varepsilon : \mathbb{D}^2 \rightarrow \mathbb{R}^k$ defined by

$$v_\varepsilon(x) = u_\varepsilon(rx + x_0), \forall x \in \mathbb{D}^2.$$

If u_ε is a solution to the PDE, when v_ε is a solution to the PDE with parameter ε . The scaling for the energy are

$$\begin{cases} e_\varepsilon(v_\varepsilon)(x) = re_\varepsilon(u)(rx + x_0), \forall x \in \mathbb{D}^2 \\ E_\varepsilon(u_\varepsilon, \mathbb{D}^2(r)) = rE_\varepsilon(v_\varepsilon, \mathbb{D}^2(1)) \text{ and } \mathbb{V}_\varepsilon(u_\varepsilon, \mathbb{D}^2(r)) = r\mathbb{V}_\varepsilon(v_\varepsilon, \mathbb{D}^2(1)) \text{ with} \end{cases}$$

$$E_\varepsilon(u, G) \equiv \int_G e_\varepsilon(u) dx \text{ and } \mathbb{V}_\varepsilon(u, G) \equiv \int_G \frac{V(u)}{\varepsilon} dx.$$

- The parameter ε as well as the energy E_ε behave as lengths
- $\varepsilon^{-1}E_\varepsilon$ is scale invariant, according to the previous scale changes.

Clearing-out for the PDE

Choose $\mu_0 > 0$ so that $B^k(\sigma_i, 2\mu_0) \cap B^k(\sigma_j, 2\mu_0) = \emptyset$ for all $i \neq j$ in $\{1, \dots, q\}$ and such that and

$$\frac{1}{2} \lambda_i^- \text{Id} \leq \nabla^2 V(y) \leq 2 \lambda_i^+ \text{Id} \quad \text{for all } i \in \{1, \dots, q\} \text{ and } y \in B(\sigma_i, 2\mu_0). \quad (11)$$

Theorem

Let $0 < \varepsilon \leq 1$ and u_ε be solution of the $(PDE)_\varepsilon$ on \mathbb{D}^2 . There exists $\eta_0 > 0$ s.t. if

$$E_\varepsilon(u_\varepsilon, \mathbb{D}^2) \leq \eta_0,$$

then there exists some $\sigma \in \Sigma$ such that

$$|u_\varepsilon(x) - \sigma| \leq \frac{\mu_0}{2}, \text{ for every } x \in \mathbb{D}^2\left(\frac{3}{4}\right),$$

We have the energy estimate, with $C_{\text{nrg}} > 0$ depending only on V

$$E_\varepsilon\left(u_\varepsilon, \mathbb{D}^2\left(\frac{5}{8}\right)\right) \leq C_{\text{nrg}} \varepsilon E_\varepsilon(u_\varepsilon, \mathbb{D}^2).$$

The previous result relies on:

Proposition

Let $0 < \varepsilon \leq 1$ and u_ε be a solution of $(PDE)_\varepsilon$ on \mathbb{D}^2 . There exists a constant $C_{\text{dec}} > 0$ such that

$$\int_{\mathbb{D}^2(\frac{9}{16})} e_\varepsilon(u_\varepsilon) dx \leq C_{\text{dec}} \left[\left(\int_{\mathbb{D}^2} e_\varepsilon(u_\varepsilon) dx \right)^{\frac{3}{2}} + \varepsilon \int_{\mathbb{D}^2} e_\varepsilon(u_\varepsilon) dx \right]. \quad (12)$$

This proposition is perhaps the **main new ingredient**: When both $E_\varepsilon(u_\varepsilon)$ and ε are **small**, it provides a fast decay of the energy on smaller balls. Iterating this decay estimate, we are led to the proof of the **Clearing-out Theorem**.

One-dimensional estimates

In dimension 1 **energy bounds** directly lead to **uniform bound**. Set $\mathbb{S}^1(r) = \{x \in \mathbb{R}^2, |x| = r\}$ and consider $u : \mathbb{S}^1(r) \rightarrow \mathbb{R}^k$.

Lemma

Let $0 < \varepsilon \leq 1$ and $0 < r < 1$ be given. There exists a constant $C_{\text{unf}} > 0$ such that, for any given $u : \mathbb{S}^1(r) \rightarrow \mathbb{R}^k$, there exists an element $\sigma \in \Sigma$ such that

$$|u(\ell) - \sigma| \leq C_{\text{unf}} \sqrt{\int_{\mathbb{S}^1(r)} e_\varepsilon(u) d\ell}, \quad \text{for all } \ell \in \mathbb{S}^1.$$

Comment On the disk \mathbb{D}^2 , the result shows that if a map has small E_ε energy, then **oscillations around** an element of Σ are small for many circles $\mathbb{S}^1(r)$.

Elements in the proof: Standard elliptic estimates:

- **uniform bounds** $|\nabla u_\varepsilon| \leq \frac{K_{dr}}{\varepsilon}$ and $|u_\varepsilon| \leq M$. In particular

$$e_\varepsilon(u_\varepsilon) \leq C_T \frac{V(u_\varepsilon)}{\varepsilon} \quad \text{on } \Theta_\varepsilon = u_\varepsilon^{-1} \left(\bigcup_{i=1}^q \mathbb{B}^k(\sigma_i, \frac{\mu_0}{4}) \right)$$

- **Pohozaev type bounds:** (specific to dimension 2) for $\delta > 0$ small, \mathcal{U} open subset

$$\frac{1}{\varepsilon} \int_{\mathcal{U}_{\frac{\delta}{2}}} V(u_\varepsilon) dx \leq C(\mathcal{U}, \delta) \int_{\mathcal{V}_\delta} e_\varepsilon(u_\varepsilon) dx, \quad \text{where}$$

$$\begin{cases} \mathcal{U}_\delta = \{x \in \Omega, \text{dist}(x, \mathcal{U}) \leq \delta\} \quad \text{and} \\ \mathcal{V}_\delta = \mathcal{U}_\delta \setminus \mathcal{U} = \{x \in \Omega, 0 \leq \text{dist}(x, \mathcal{U}) \leq \delta\}. \end{cases}$$

Remark

A related relation is: For any radius $0 < r \leq 1$

$$\frac{1}{\varepsilon^2} \int_{\mathbb{D}^2(r)} V(u_\varepsilon) = \frac{r}{4} \int_{\partial D^2(r)} \left(\left| \frac{\partial u}{\partial \tau} \right|^2 - \left| \frac{\partial u_\varepsilon}{\partial r} \right|^2 + \frac{2}{\varepsilon^2} V(u) \right) d\tau.$$

This identity leads to the monotonicity formula

$$\frac{d}{dr} \left(\frac{E_\varepsilon(u_\varepsilon, \mathbb{D}^2(r))}{r} \right) = \frac{1}{r^2} \int_{\mathbb{D}^2(r)} \xi_\varepsilon(u_\varepsilon) dx + \frac{1}{r} \int_{S^1(r)} \left| \frac{\partial u_\varepsilon}{\partial r} \right|^2 d\ell.$$

Energy on level sets

let $u_\varepsilon : \mathbb{D}^2 \rightarrow \mathbb{R}^k$ be solution to the $(PDE)_\varepsilon$. Assume we are given $\varrho_\varepsilon \in [\frac{1}{2}, \frac{3}{4}]$, $0 < \kappa < \frac{\mu_0}{2}$, $\sigma_{\text{main}} \in \Sigma$ such that

$$|u_\varepsilon - \sigma_{\text{main}}| < \kappa \text{ on } \partial \mathbb{D}^2(\varrho_\varepsilon). \quad (13)$$

Consider $Y_\varepsilon(\varrho_\varepsilon, \kappa)$ defined by

$$Y_\varepsilon(\varrho_\varepsilon, \kappa) = \left\{ x \in \mathbb{D}^2(\varrho_\varepsilon) \text{ such that } |u_\varepsilon(x) - \sigma_i| < \kappa, \text{ for some } i = 1 \dots q \right\}$$

The set $Y_\varepsilon(\varrho_\varepsilon, \kappa)$ is a truncation of the domain with points with values far from Σ removed. The solution u_ε on $Y_\varepsilon(\varrho, \kappa)$ is close, at least when the energy is small, to one of the points σ_j : Near this point the potential is close to a quadratic potential. We have

Proposition

We have, for $C_Y > 0$, under above assumptions

$$\int_{Y_\varepsilon(\varrho_\varepsilon, \kappa_\varepsilon)} e_\varepsilon(u_\varepsilon)(x) dx \leq C_Y \left[\kappa \int_{\mathbb{D}^2(\varrho_\varepsilon)} \frac{V(u_\varepsilon)}{\varepsilon} dx + \varepsilon \int_{\partial \mathbb{D}^2(\varrho_\varepsilon)} e_\varepsilon(u_\varepsilon) d\ell \right].$$

The next step is to specify the result of the previous proposition for special choices of κ and ρ_ε . More precisely, we choose

$$\rho_\varepsilon = r_\varepsilon \text{ and } \kappa_\varepsilon = 2C_{bd}\sqrt{E_\varepsilon(u_\varepsilon)}, C_{bd} > 0 \text{ a constant,}$$

where $\frac{3}{4} \leq r_\varepsilon \leq 1$ is obtained by the following mean value argument:

Lemma

Let $0 \leq r_0 < r_1 \leq 1$ and $u : \mathbb{D}^2 \rightarrow \mathbb{R}^k$ be given. There exists a radius $r_\varepsilon \in [r_0, r_1]$ s.t.

$$\int_{S^1(r_\varepsilon)} e_\varepsilon(u) d\ell \leq \frac{1}{r_1 - r_0} E_\varepsilon(u, \mathbb{D}^2(r_1)).$$

This specification yields

$$\int_{Y_\varepsilon(r_\varepsilon, \kappa_\varepsilon)} e_\varepsilon(u_\varepsilon)(x) dx \leq 2C_Y \left[C_{bd}\sqrt{E_\varepsilon(u_\varepsilon)} \int_{\mathbb{D}^2(\rho_\varepsilon)} \frac{V(u_\varepsilon)}{\varepsilon} dx + \varepsilon \int_{\partial\mathbb{D}^2(\rho_\varepsilon)} e_\varepsilon(u_\varepsilon) d\ell \right].$$

Proposition

There exists a constant $C_V > 0$ such that

$$\frac{1}{\varepsilon} \int_{\mathbb{D}^2(\frac{5}{8})} V(u_\varepsilon) dx \leq C_V \left[\left(\int_{\mathbb{D}^2} e_\varepsilon(u_\varepsilon)(x) dx \right)^{\frac{3}{2}} + \varepsilon \int_{\mathbb{D}^2} e_\varepsilon(u_\varepsilon)(x) dx \right].$$

We may assume [the energy is small](#) and consider the restriction of u_ε to the set $\Omega = \mathbb{D}^2(r_\varepsilon)$. The [coarea formula](#) and a [mean-value argument](#) yield some $s_\varepsilon \in [C_{\text{bd}} \sqrt{E_\varepsilon(u)}, 2C_{\text{bd}} \sqrt{E_\varepsilon(u)}]$ such that [the curve](#) $\mathcal{C}_\varepsilon \equiv w^{-1}(s_\varepsilon) \cap \mathbb{D}^2(r_\varepsilon)$, where $w = |u_\varepsilon - \sigma|$, verifies

$$\mathcal{L}(\mathcal{C}_\varepsilon) \leq \mathcal{L}(w^{-1}(s_\varepsilon)) \leq C_L \sqrt{E_\varepsilon(u)}. \quad (14)$$

By a mean value argument, we may then choose a new radius $\rho_\varepsilon \in [\frac{5}{8}, \tau_\varepsilon]$ such that

$$\begin{cases} |u - \sigma| \leq C_{bd} \sqrt{E_\varepsilon(u)} \text{ on } \mathbb{S}^1(\rho_\varepsilon) \\ \int_{\mathbb{S}^1(\rho_\varepsilon)} e_\varepsilon(u_\varepsilon) d\ell \leq \frac{1}{16} \int_{G_\varepsilon} e_\varepsilon(u_\varepsilon) dx. \end{cases}$$



Invoking the potential estimate we are led to

$$\frac{1}{\varepsilon} \int_{\mathbb{D}^2(\varrho_\varepsilon)} V(u_\varepsilon) \leq \frac{\varrho_\varepsilon}{8} \int_{\Upsilon_\varepsilon(\varrho_\varepsilon, \kappa_\varepsilon)} e_\varepsilon(u_\varepsilon) dx \leq \frac{1}{2} \int_{\Upsilon_\varepsilon(\varrho_\varepsilon, \kappa_\varepsilon)} e_\varepsilon(u_\varepsilon) dx. \quad (15)$$

which combined with previous estimates yield the conclusion.

Thank you for your attention!