Local invariant manifolds for delay differential equations with states in the Fréchet space $C^1((-\infty,0],\mathbb{R}^n)$

Hans-Otto Walther

Dynamics of Evolution Equations
Dedicated to the memory of Prof. Jack Hale
Luminy, March 21-25, 2016

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 $g:\mathbb{R}
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Solution on
$$(t_0, t_1)$$
, $t_0 < t_1 \le \infty$,

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 cont diff, $x_t \in U$ for $t_0 < t < t_1$,

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IVP

$$x'(t) = f(x_t)$$
 for $t > 0$, $x_0 = \phi$ (1)

Fix a > 0. $B_a \subset C$ given by

$$\lim_{t\to -\infty}\phi(t)e^{at}=0$$

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(e) linear extensions $D_e f(\phi): B_a \to \mathbb{R}^n$ of $Df(\phi), \phi \in U$, and

$$U \times B_a \ni (\phi, \chi) \mapsto D_e f(\phi, \chi) \in \mathbb{R}^n$$

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continuous,

- compare almost Fréchet differentiable,

Mallet-Paret, Nussbaum, Paraskevopoulos (1994)

(lbd) for every $\phi\in U$ there are a neighbourhood $N\subset U$ and r>0 such that for all ψ,χ in N,

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Then

$$X_f = \{ \phi \in U : \phi'(0) = f(\phi) \}$$

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At stationary points $\sigma \in X_f$, W_a^s and W_a^u

Extension (W, 2013) to nonautonomous eqs $x'(t) = f(t, x_t)$,

$$x'(t) = \int_0^t \dots$$
, Volterra

$$x'(t) = ax(\lambda t) + bx(t), \quad 0 < \lambda < 1, \quad \text{pantograph}$$

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Deficiency - B_a^1 misses many solution segments:

Almost all eigensolutions $t\mapsto\Re\,e^{zt}$ of

$$y'(t) = \alpha y(t - r)$$

grow too fast at $-\infty$

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? IVP (1), cont diff solution operators on a manifold in \mathcal{C}^1 ?

Calculus in Fréchet spaces : $g : F \supset U \rightarrow G$ cont diff (MB) iff all

$$Dg(u)v = \lim_{0 \neq h \to 0} \frac{1}{h} (g(u+hv) - g(u)) \in G$$

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In infinite dim Banach spaces, weaker than cont diff (Fréchet)



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Hypothesis (lbd) ??

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 prolongation,

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$$P\sigma_d = \sigma$$

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$$x'(t) = f_d(x_t)$$
 for $t > 0$, $x_0 = \chi$

(segments on [-d,0]) defines semiflow S_d on

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Stationary point σ_d

$$W_d^s$$
 (and W_d^u , W_d^c) ((Krishnan, 1998); Krisztin, W (\leq 2006)) codim $W_d^s=n+\dim W_d^u+\dim W_d^c$

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Proposition: $g: F \supset \mathcal{O} \rightarrow G$ cont diff (MB),

 $M \subset G$ C^1 -submanifold, codim $M < \infty$,

$$Dg(x)F + T_{g(x)}M = G \implies$$

for some neighbourhood \mathcal{N} of x,

 $\mathcal{N} \cap g^{-1}(M)$ C^1 -submanifold, same codimension, ...

Properties of $W^s: W^s \subset X$,

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 exponentially as $t
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Segments $x_t \approx \sigma$ of solutions of $x'(t) = f(x_t)$ with

$$x(t)
ightarrow \sigma(0) \quad (t
ightarrow \infty)$$
 exponentially belong to W^s

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$$f_a:B^1_a\supset U_a\to \mathbb{R}^n$$
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 f_a cont diff (F), (lbd), (e)

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 defines semiflow S_a on $X_a=\{\psi\in U_a:\psi'(0)=f_a(\psi)\}$ Stationary point $\sigma\in X_a$ $(W_a^s \text{ and}) \qquad W_a^u \text{ of } S_a \text{ at } \sigma\in X_a$

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Stationary point $\sigma \in X_a$

$$(W_a^s \text{ and})$$
 $W_a^u \text{ of } S_a \text{ at } \sigma \in X_a$

$$W_a^u = w(Y_{a,u,\epsilon})$$

 $w: Y_{a,u} \supset Y_{a,u,\epsilon} \to B^1_a$ cont diff (F), parametrization

 $Y_{a,u,\epsilon}$ small ball, center 0, in $Y_{a,u}=T_{\sigma}W_a^u$,

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 $Y_{\mathsf{a},u,\epsilon}$ small ball, center 0, in $Y_{\mathsf{a},u} = \mathcal{T}_\sigma W^u_{\mathsf{a}}$,

$$W^u =_{def} JW^u_a = Jw(Y_{a,u,\epsilon})$$

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 $Y_{\mathsf{a},u,\epsilon}$ small ball, center 0, in $Y_{\mathsf{a},u} = T_\sigma W^u_{\mathsf{a}}$,

$$W^u =_{def} JW^u_a = Jw(Y_{a,u,\epsilon})$$

 C^1 -submanifold of C^1 because of

 $J \circ Dw(0)$ injective and dim $Y_{u,a} < \infty$.

Proposition: $j: E \supset \mathcal{O} \to G$ cont diff (MB), dim $E < \infty$, $x \in \mathcal{O}$, Dj(x) injective \Longrightarrow for some open neighbourhood \mathcal{O}_x of x in E, $j(\mathcal{O}_x)$ C^1 -submanifold of G, same dimension, ...

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 $W^u \subset X$

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Center manifolds for S at $\sigma \in X$ — by a third approach

Center manifolds for S at $\sigma \in X$ — by a third approach Thank you !

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